SHARP EXISTENCE AND CLASSIFICATION RESULTS FOR NONLINEAR ELLIPTIC EQUATIONS IN $\mathbb{R}^N \setminus \{0\}$ WITH HARDY POTENTIAL

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ABSTRACT. For $N \geq 3$, by the seminal paper of Brezis and Véron (Arch. Rational Mech. Anal. 75(1):1–6, 1980/81), no positive solutions of $-\Delta u + u^q = 0$ in $\mathbb{R}^N \setminus \{0\}$ exist if $q \geq N/(N-2)$; for 1 < q < N/(N-2) the existence and profiles near zero of all positive $C^1(\mathbb{R}^N \setminus \{0\})$ solutions are given by Friedman and Véron (Arch. Rational Mech. Anal. 96(4):359–387, 1986).

In this paper, for every q > 1 and $\theta \in \mathbb{R}$, we prove that the nonlinear elliptic problem (\star) $-\Delta u - \lambda |x|^{-2} u + |x|^{\theta} u^{q} = 0$ in $\mathbb{R}^{N} \setminus \{0\}$ with u > 0 has a $C^{1}(\mathbb{R}^{N} \setminus \{0\})$ solution if and only if $\lambda > \lambda^{*}$, where $\lambda^{*} = \Theta(N - 2 - \Theta)$ with $\Theta = (\theta + 2)/(q - 1)$. We show that (a) if $\lambda > (N - 2)^{2}/4$, then $U_{0}(x) = (\lambda - \lambda^{*})^{1/(q-1)}|x|^{-\Theta}$ is the only solution of (\star) and (b) if $\lambda^{*} < \lambda \leq (N - 2)^{2}/4$, then all solutions of (\star) are radially symmetric and their total set is $U_{0} \cup \{U_{\gamma,q,\lambda}: \gamma \in (0,\infty)\}$. We give the precise behavior of $U_{\gamma,q,\lambda}$ near zero and at infinity, distinguishing between $1 < q < q_{N,\theta}$ and $q > \max\{q_{N,\theta}, 1\}$, where $q_{N,\theta} = (N + 2\theta + 2)/(N - 2)$.

In addition, for $\theta \leq -2$ we settle the structure of the set of all positive solutions of (\star) in $\Omega \setminus \{0\}$, subject to $u|_{\partial\Omega} = 0$, where Ω is a smooth bounded domain containing zero, complementing the works of Cirstea (Mem. Amer. Math. Soc. 227, 2014) and Wei–Du (J. Differential Equations 262(7):3864–3886, 2017).

1. INTRODUCTION AND MAIN RESULTS

1.1. Introduction. In two groundbreaking papers [33, 34], Serrin studied a priori estimates of solutions, the removability of singularities, and the behavior of isolated singularities for general quasilinear elliptic divergence-form equations in $\Omega \setminus \{0\}$, where $\Omega \subseteq \mathbb{R}^N$ is a domain containing zero. The history of the isolated singularity problem, its challenges and significant achievements up to 1996 have been beautifully portrayed by Véron [41]. To address the interior isolated singularity problem for nonlinear elliptic equations under conditions outside the range of Serrin's papers is a very difficult and multifaceted task. This has fueled a lot of research in the last decade approaching the challenge from different viewpoints in specific and particular directions. A very active line of research (see, for example, [3, 11, 13, 17-19, 21, 22, 28, 29, 43, 44]) is to explore the intricate links between the isolated singularity problem and singular potentials. Among these, the celebrated Hardy–Schrödinger operator (see \mathbb{L}_{λ} in (1.6)) and, more generally, the Hardy–Sobolev operator play a prominent role. Elliptic differential operators of this type are important in the famous Caffarelli-Kohn-Nirenberg inequalities, being analyzed in connection with the best constants and symmetry (or symmetry breaking) of extremal functions [8,9]. Recent developments and challenges on such topics, which have significance to diverse areas such as quantum mechanics, astrophysics and Riemannian geometry, are expounded by Ghoussoub and Robert in [26].

The Hardy-type inequalities among others reflect amazing mathematical structures in connection with a variety of "energies" controlled by "entropy" associated with the Laplacian. For

Date: August 31, 2020.

a bounded domain $\Omega \subset \mathbb{R}^N$ $(N \geq 3)$ with $0 \in \Omega$, the classical Hardy inequality states that

$$\int_{\Omega} |\nabla u|^2 \, dx \ge \frac{(N-2)^2}{4} \, \int_{\Omega} \frac{u^2}{|x|^2} \, dx \quad \text{for all } u \in H^1_0(\Omega). \tag{1.1}$$

It is well-known that $\lambda_H := (N-2)^2/4$ is the best constant for the inequality in (1.1). However, λ_H is never attained in $H_0^1(\Omega)$ when Ω is bounded, in which case a remainder was shown to exist by Brezis and Vázquez [5]. The improvements of this inequality on bounded domains, involving for example the first zero of the Bessel function, have been lately linked with Sturm's theory regarding the oscillatory behavior of certain linear ordinary differential equations. The Hardy inequality and its various refinements [1, 20, 24] have found rich and diverse applications including the analysis of the stability of solutions of semilinear elliptic and parabolic equations [5,7], the asymptotic behavior of the heat equation with singular potentials [38] and the stability of eigenvalues in elliptic problems with perturbed Schrödinger operators [2]. For new perspectives and applications of functional inequalities, we refer to Ghoussoub and Moradifam's book [25].

In this paper, we study elliptic equations involving the Hardy–Schrödinger operator such as

$$-\Delta u - \frac{\lambda}{|x|^2} u + |x|^{\theta} u^q = 0 \quad \text{in } \Omega \setminus \{0\}, \quad u > 0 \quad \text{in } \Omega \setminus \{0\}, \tag{1.2}$$

where $\Omega \subseteq \mathbb{R}^N$ $(N \ge 3)$ is either \mathbb{R}^N or an open set Ω_0 that contains zero, or an open set Ω_{∞} that contains $\{x \in \mathbb{R}^N : |x| > R\}$ for R > 0; we assume $q, \lambda, \theta \in \mathbb{R}$ and focus on the super-linear case q > 1. In the sub-linear case 0 < q < 1, the classification and limit behaviors of the non-negative solutions of (1.2) in $\mathbb{R}^N \setminus \{0\}$ are known from the work [3] of Bidaut-Véron and Grillot.

From now on, we assume q > 1. For the long history associated with the study of problem (1.2), we refer to [13, 28, 42] and the references cited therein. When $\lambda = \theta = 0$ and q > 1, the study of the local and global solutions of (1.2) has been pioneered by Brezis–Véron [6] and Véron [39, 40]. Their results were generalized to *p*-Laplacian type equations with 1 by Friedman and Véron [23] for <math>p - 1 < q < N(p - 1)/(N - p) and by Vázquez and Véron [37] for $q \ge N(p - 1)/(N - p)$. More recent generalizations exist in various directions, but without a Hardy potential [4, 10, 12, 14, 15, 35].

As a major advance in this paper, we unveil the structure of the set of solutions of (1.2) when $\Omega = \mathbb{R}^N$ for every $\theta, \lambda \in \mathbb{R}$ and q > 1. We give sharp existence results of all solutions of (1.2), along with their precise behavior near the singular point x = 0 and at infinity (see Theorems 1.1, 1.4 and 1.5 or Corollary 9.1). In addition, we provide the existence and profile near zero for all solutions of (1.2) when Ω is a bounded domain of \mathbb{R}^N with $0 \in \Omega$ and smooth boundary $\partial\Omega$ on which we impose a homogeneous (or non-homogeneous) Dirichlet boundary condition (see Theorem 1.3 or Corollaries 9.4–9.8). Using the Kelvin transform, our results can be reformulated for problem (1.2) when Ω is an exterior domain. In Section 1.2 we state our main results, which can be applied to equations where the Hardy–Schrödinger operator is replaced by more general operators, see Section 1.3.

The difficulties in deciphering the profiles near zero for the solutions of (1.2) with $\Omega = \Omega_0$ arise from and vary according to the position of λ with respect to $\lambda_H = (N-2)^2/4$, the best constant in the Hardy inequality, and the position of θ relative to -2. When $\theta > -2$, the asymptotic behavior near zero of the solutions of (1.2) has recently been classified by Cîrstea [13] for $\lambda \leq \lambda_H$ (relying on the fundamental solutions of the Hardy–Schrödinger operator), and by Wei and Du [42] for $\lambda > \lambda_H$. The methods in the latter case use among other things an approximation of λ_H by first eigenvalues of suitably modified eigenvalue problems and cannot be applied to the former case and vice versa.

We stress that for $\theta \leq -2$, unlike $\theta > -2$, every solution of (1.2) with $\Omega = \Omega_0$ is bounded near zero for every $\lambda \in \mathbb{R}$ (see Lemma 4.2 or [42, Proposition 2.7]). Since singular solutions were the main interest of [13] and [42], the precise asymptotic behavior near zero was not pursued there

for $\theta \leq -2$ in (1.2). What this means (when using the Kelvin transform) is that the asymptotic behavior at *infinity* for the solutions of (1.2) with $\Omega = \Omega_{\infty}$ is still open for $\theta > -2$. We settle this issue in Theorem 2.2 as a result of Theorem 1.2.

By means of a new and unified approach, in Theorem 1.2 we recover and extend to every $\theta \leq -2$ the results in [42] for $\lambda > \lambda_H$ and also to the relevant maximal range for $\lambda \leq \lambda_H$ (see Section 1.2 for details).

Our findings differ according to four cases: $(\mathcal{U}), (\mathcal{M}_1), (\mathcal{M}_2)$ and (\mathcal{N}) . The first one corresponds to $\lambda > \lambda_H$ and every $\theta \in \mathbb{R}$, whereas the latter three situations pertain to $\lambda \leq \lambda_H$ and arise from the position of θ with respect to two critical exponents denoted by θ_- and θ_+ , where

$$\theta_{\pm} := p_{\pm} (q-1) - 2 \quad \text{and} \quad p_{\pm} := \frac{N-2}{2} \pm \sqrt{\lambda_H - \lambda}.$$
(1.3)

A first difference can be remarked at this stage compared with previous studies: when $\lambda > \lambda_H$ in our approach we can deal with every $\theta \in \mathbb{R}$ at once. On the other hand, for $\lambda \leq \lambda_H$, we emphasize that the position of θ is not analyzed with respect to -2 but rather with two critical exponents θ_{\pm} defined in (1.3). This is because we rely on the Kelvin transform, the effect of which when applied to a solution of (1.2) is to render an equation of the same type as (1.2) in which only θ changes, becoming $\hat{\theta} := (N-2) q - (N+2+\theta)$. Remark that $p_+ + p_- = N - 2$ and $p_+p_- = \lambda$. Thus, p_{\pm} are the roots of $\ell = 0$ seen as a quadratic equation in Θ , where for every $\theta \in \mathbb{R}$, we define

$$\Theta := \frac{\theta + 2}{q - 1} \quad \text{and} \quad \ell(\theta) = \ell := \Theta^2 - (N - 2)\Theta + \lambda.$$
(1.4)

In this paper, we give the structure of the set of *all* solutions of (1.2) with $\Omega = \mathbb{R}^N$ as follows:

- (a) A uniqueness result in Theorem 1.1 for Case (\mathcal{U}) , where
- $(\mathcal{U}) \ \lambda > \lambda_H \text{ and } \theta \in \mathbb{R};$
- (b) A multiplicity result in Theorem 1.4 in relation to Cases (\mathcal{M}_1) and (\mathcal{M}_2) :
 - $(\mathcal{M}_1) \ \lambda \leq \lambda_H \text{ and } \theta < \theta_-;$
- (\mathcal{M}_2) $\lambda \leq \lambda_H$ and $\theta > \theta_+$. (Here, we always have $\theta_+ > -2$ since q > 1.)
- (c) Non-existence of solutions of (1.2) in Theorem 1.5 for Case (\mathcal{N}) , namely,
 - $(\mathcal{N}) \ \lambda \leq \lambda_H \text{ and } \theta_- \leq \theta \leq \theta_+.$

In Cases (\mathcal{U}) , (\mathcal{M}_1) and (\mathcal{M}_2) , we see that $\ell > 0$ and a radial solution of problem (1.2) is given by

$$U_0(x) = U_0(|x|) := \ell^{1/(q-1)} |x|^{-\Theta} \quad \text{for every } x \in \mathbb{R}^N \setminus \{0\}.$$
(1.5)

The Kelvin transform in Section 2 reveals an intimate connection between Case (\mathcal{M}_1) and Case (\mathcal{M}_2) —the behavior near zero for a solution of (1.2) in one of these cases leads to knowledge of the behavior at infinity for another solution of (1.2) in the other case. In Case (\mathcal{M}_2) the classification of the behavior near zero of the solutions of problem (1.2) given in [13] is closely linked with the fundamental solutions Φ^{\pm}_{λ} of the Hardy–Schrödinger operator $\mathbb{L}_{\lambda} := \Delta + \lambda |x|^{-2}$. (We recall this classification in Theorem 2.1.) When $\lambda \leq \lambda_H$, let Φ^{\pm}_{λ} be the fundamental solutions of the linear equation

$$-\mathbb{L}_{\lambda}\Phi = 0 \quad \text{in } B_1(0) \setminus \{0\}, \quad \text{where} \quad \mathbb{L}_{\lambda} := \Delta + \lambda \, |x|^{-2}. \tag{1.6}$$

We set $\Phi_{\lambda}^{-}(x) = |x|^{-p_{-}}$ for each $x \in \mathbb{R}^{N} \setminus \{0\}$ and we define Φ_{λ}^{+} as follows

$$\Phi_{\lambda}^{+}(x) = \begin{cases} |x|^{-p_{+}} & \text{for every } x \in \mathbb{R}^{N} \setminus \{0\} & \text{if } \lambda < \lambda_{H}, \\ |x|^{-\frac{N-2}{2}} \log\left(1/|x|\right) & \text{for every } 0 < |x| < 1 & \text{if } \lambda = \lambda_{H}. \end{cases}$$
(1.7)

Then, Φ_{λ}^{-} satisfies (1.6) in $\mathcal{D}'(\mathbb{R}^{N})$ and $\lambda | \cdot |^{-2} \Phi_{\lambda}^{-}(\cdot)$ is locally integrable in \mathbb{R}^{N} . (The same applies to Φ_{λ}^{+} if $0 < \lambda < \lambda_{H}$.)

For $\Omega = \mathbb{R}^N$, in Case (\mathcal{M}_1) , like in Case (\mathcal{M}_2) , we prove in Theorem 1.4 that (1.2) has infinitely many solutions, all radially symmetric satisfying

$$\lim_{|x|\to 0} \frac{u(x)}{U_0(x)} = 1 \text{ in Case } (\mathcal{M}_1) \text{ and } \lim_{|x|\to\infty} \frac{u(x)}{U_0(x)} = 1 \text{ in Case } (\mathcal{M}_2).$$

In addition, we find the following:

• For every θ in Case (\mathcal{M}_2) , there exists a unique solution $u_{1,\theta}$ of (1.2) with $\Omega = \mathbb{R}^N$, subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = 1$, where Φ_{λ}^+ is given by (1.7). Then, $U_0 \cup \{\mu^{\Theta}u_{1,\theta}(\mu \cdot) : \mu \in (0,\infty)\}$ give all solutions of (1.2) in $\mathbb{R}^N \setminus \{0\}$.

• For each θ in Case (\mathcal{M}_1) , the set of all solutions of (1.2) with $\Omega = \mathbb{R}^N$ is $U_0 \cup \{\mu^{\Theta} U_{1,\theta}(\mu \cdot) : \mu \in (0,\infty)\}$, where $U_{1,\theta}$ is the Kelvin transform of $u_{1,\widehat{\theta}}$ with $\widehat{\theta} := (N-2) q - (N+2+\theta)$, namely, $U_{1,\theta}(x) := |x|^{2-N} u_{1,\widehat{\theta}}(x/|x|^2)$ for $x \in \mathbb{R}^N \setminus \{0\}$. If θ is in Case (\mathcal{M}_1) , then $\widehat{\theta}$ is in Case (\mathcal{M}_2) and $\ell(\theta) = \ell(\widehat{\theta})$.

We bring to light several interesting features for the solutions of (1.2) when considered globally for $\Omega = \mathbb{R}^N$ rather than locally, say for $\Omega = B_1(0)$. A significant difference between local and global solutions is that, whenever it exists, a solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$ becomes radially symmetric (see Theorems 1.1 and 1.4). Another difference is that a host of solutions of (1.2) that exist in $\Omega \setminus \{0\}$, where Ω is a smooth bounded domain containing zero, cannot be extended as solutions of (1.2) in $\mathbb{R}^N \setminus \{0\}$. This becomes apparent by comparing Theorems 1.1, 1.4 and 1.5 with Theorem 1.3 (see also Remark 9.9).

Definition 1. By a solution (sub-solution, super-solution) of (1.2), we mean a positive function $u \in C^1(\Omega \setminus \{0\})$ such that for all functions (non-negative functions) $\varphi \in C_c^1(\Omega \setminus \{0\})$, we have

$$\int_{\Omega} \nabla u \cdot \nabla \varphi \, dx - \int_{\Omega} \frac{\lambda}{|x|^2} u \, \varphi \, dx + \int_{\Omega} |x|^{\theta} u^q \, \varphi \, dx = 0 \quad (\le 0, \ge 0). \tag{1.8}$$

We denote by $C_c^1(\Omega \setminus \{0\})$ the set of functions in $C^1(\Omega \setminus \{0\})$ with compact support in $\Omega \setminus \{0\}$.

1.2. Main results. We show that Case (\mathcal{U}) resembles Case (\mathcal{M}_1) (respectively, Case (\mathcal{M}_2)) only when it comes to the asymptotic behavior near zero (respectively, at infinity) for every solution of (1.2) with $\Omega = \Omega_0$ (respectively, $\Omega = \Omega_\infty$). In other respects, Case (\mathcal{U}) is different from the rest. Our first result shows the reason.

Theorem 1.1 (Uniqueness). In Case (\mathcal{U}) , U_0 in (1.5) is the unique solution of (1.2) for $\Omega = \mathbb{R}^N$.

To our best knowledge, this result is completely new. The crux of the proof is to show that in Case (\mathcal{U}) , U_0 models the behavior near zero for every solution of (1.2), which also happens in Case (\mathcal{M}_1) .

Theorem 1.2 (Classification of behavior near zero, Cases (\mathcal{U}) and (\mathcal{M}_1)). In Case (\mathcal{U}) and Case (\mathcal{M}_1) , every solution of (1.2) with $\Omega = \Omega_0$ exhibits near zero the limit behavior

$$\lim_{|x| \to 0} \frac{u(x)}{U_0(x)} = 1.$$
(1.9)

The advance made in Theorem 1.2 is to remove the restriction $\theta > -2$ imposed in [13] for Case (\mathcal{M}_1) and in [42] for Case (\mathcal{U}) . When $\theta \leq -2$ in Case (\mathcal{U}) a precise asymptotic behavior near zero remained open: it was shown only that every solution of (1.2) is bounded near zero [42, Proposition 2.7] (see Lemma 4.2 for another proof). The method in [42] is different than in [13] and neither treatment could be adapted to cover the full range of Theorem 1.2. Indeed, the techniques in [13] for Case (\mathcal{M}_1) rely on the fundamental solutions of the Hardy–Schrodinger

operator \mathbb{L}_{λ} in (1.6) and thus cannot be extended to tackle Case (\mathcal{U}) in Theorem 1.2. On the other hand, the results in [42] depend on $\theta > -2$ and $\lambda > \lambda_H$ to get an approximation (performed in [44]) of the Hardy constant λ_H by first eigenvalues of suitably modified eigenvalue problems of $-\Delta\phi = \lambda |x|^{-2}\phi$ in $H_0^1(\Omega)$, see [42, Lemma 2.3]; the analysis is also based on [42, Proposition 2.5] giving the existence and uniqueness of the solution to (1.2), where Ω is a smooth bounded domain containing zero, subject to a zero Dirichlet condition on $\partial\Omega$. But such a solution fails to exist in Case (\mathcal{M}_1) as we shall prove in Theorem 1.3.

We provide a new and unified proof of Theorem 1.2 that in our opinion is simpler than in [13] and [42]. We describe here the novelty of our approach. Unlike the method in [13], we do not use the fundamental solutions of the operator \mathbb{L}_{λ} in (1.6). Instead, we construct explicit local sub-solutions and super-solutions of (1.2) with the advantage of unifying the treatment of Cases (\mathcal{M}_1) and (\mathcal{U}). We also reason differently than in [42] for $\theta > -2$ in Case (\mathcal{U}) since our proof of (1.9) does not rely on the existence and uniqueness of the solution to (1.14) with h = 0. In fact, we use the opposite strategy. First, without any concern for the existence issue, we prove that any solution of (1.2) satisfies (1.9) in Cases (\mathcal{U}) and (\mathcal{M}_1). Then, with this precise behavior near zero, we infer in Theorem 1.3 that (1.14) has at most one solution via the comparison principle in Lemma 4.1, whereas we obtain a solution as a limit of solutions to approximate boundary value problems. (For the existence of a solution in Case (\mathcal{M}_1), the condition $h \not\equiv 0$ in (1.14) is necessary.)

What sets apart Case (\mathcal{U}) and Case (\mathcal{M}_1) from the remaining cases is that every solution u of (1.2) with $\Omega = \Omega_0$ satisfies

$$\liminf_{|x| \to 0} \frac{u(x)}{U_0(x)} > 0. \tag{1.10}$$

We prove this fact in Lemma 3.1 by devising an explicit family $\{w_{\delta}\}_{\delta>0}$ of "rough" sub-solutions of (1.2) in $\mathbb{R}^N \setminus \overline{B_{\delta}(0)}$, satisfying $w_{\delta} = 0$ on $\partial B_{\delta}(0)$ and $\lim_{\delta \to 0^+} w_{\delta}(x) = c U_0(x)$ for every $x \in \mathbb{R}^N \setminus \{0\}$, where c > 0 is any suitably small constant. More precisely, we define w_{δ} as follows

$$w_{\delta}(x) := c U_0(x) \left[1 - \left(\frac{\delta}{|x|}\right)^{\alpha} \right]^{\frac{1}{\sqrt{\alpha}}} \quad \text{for every } |x| \ge \delta, \tag{1.11}$$

where we fix $\alpha > 0$ small, depending only on N, q, θ and λ . It turns out that w_{δ} satisfies the above properties for every $c \in (0, c_{\alpha})$, where $c_{\alpha} > 0$ depends on α , but not on δ . With a suitable choice of the constant $c = c(r_0, u)$ such that $u \ge w_{\delta}$ on $\partial B_{r_0}(0)$, where $r_0 > 0$ is such that $\overline{B_{r_0}(0)} \subset \Omega$, the comparison principle in Lemma 4.1 implies that $u \ge w_{\delta}$ for every $\delta \le |x| \le r_0$. By letting $\delta \to 0^+$, we obtain (1.10). We use the term "rough" in relation to the sub-solution w_{δ} to indicate that at this stage we get $\liminf_{|x|\to 0} u(x)/U_0(x) \ge c$ for a constant c > 0 that is *not* optimal.

To complete the proof of Theorem 1.2 it remains to show that (1.10) yields (1.9). This is achieved in Proposition 5.2 by a unified construction of refined local sub/super-solutions of (1.2) in $B_1(0) \setminus \{0\}$. These are explicitly given in (1.12), working in Cases (\mathcal{U}), (\mathcal{M}_1) and (\mathcal{M}_2) (see Lemma 5.1 for details). For every $\varepsilon \in (0, 1)$ and $\eta > 0$, we define $w_{\varepsilon,\eta}^{\pm}$ in $\mathbb{R}^N \setminus \{0\}$ as follows

$$w_{\varepsilon,\eta}^{-}(x) := (1-\varepsilon) U_0(x) |x|^{\eta} \left(1 + \frac{|x|^{\alpha}}{\nu}\right)^{-\frac{1}{\sqrt{\alpha}}},$$

$$w_{\varepsilon,\eta}^{+}(x) := (1+\varepsilon) U_0(x) |x|^{-\eta} \left(1 + \frac{|x|^{\alpha}}{\nu}\right)^{\frac{1}{\sqrt{\alpha}}},$$
(1.12)

where $\alpha > 0$ is suitably fixed, depending only on N, q, θ and λ , whereas $\nu > 0$ is arbitrary. Such a construction, which we motivate in Section 5.1, appears here for the first time and is robust enough to deal with the Hardy potential in the nonlinear elliptic equation (1.2).

Theorem 1.1 follows readily from Theorem 1.2. Indeed, by proving in Case (\mathcal{U}) that there is only one asymptotic behavior near zero as in (1.9), using the Kelvin transform, we gain a unique behavior at infinity for *every* solution of (1.2) with $\Omega = \Omega_{\infty}$, namely,

$$\lim_{|x| \to \infty} \frac{u(x)}{U_0(x)} = 1.$$
(1.13)

Then, using Lemma 4.1, we derive that U_0 is in Case (\mathcal{U}) the only solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$. In contrast, we prove in Theorem 1.4 that (1.2) in $\mathbb{R}^N \setminus \{0\}$ has infinitely many solutions in Case (\mathcal{M}_1) and Case (\mathcal{M}_2) , whereas no solutions exist in Case (\mathcal{N}) (see Theorem 1.5).

In Theorem 1.3 we extend some results from [13] and [42] and find new ones about the solutions of (1.2), subject to a Dirichlet boundary condition on $\partial\Omega$. For every q > 1 and $\lambda, \theta \in \mathbb{R}$, we address the existence, uniqueness or multiplicity of solutions to the nonlinear elliptic problem

$$\begin{cases} -\Delta u - \frac{\lambda}{|x|^2} u + |x|^{\theta} u^q = 0 & \text{in } \Omega \setminus \{0\}, \\ u = h \ge 0 & \text{on } \partial\Omega, \quad u > 0 & \text{in } \Omega \setminus \{0\}, \end{cases}$$
(1.14)

where Ω is a smooth bounded domain containing the origin of \mathbb{R}^N $(N \ge 3)$ and $h \in C(\partial \Omega)$ is a non-negative function. By a solution of (1.14), we mean a function $u_h \in C^1(\Omega \setminus \{0\}) \cap C(\overline{\Omega} \setminus \{0\})$ that is positive in $\Omega \setminus \{0\}$ such that $u_h|_{\partial\Omega} = h$ and u_h satisfies (1.2) in $\mathcal{D}'(\Omega \setminus \{0\})$.

Theorem 1.3 (Existence, uniqueness/multiplicity results for (1.14)). Let $\Omega \subseteq \mathbb{R}^N$ be a smooth bounded domain containing zero. Let $h \in C(\partial \Omega)$ be any non-negative function.

(1) Let Case (U) hold. Then, problem (1.14) has a unique solution u_h . Moreover, if $\Theta < 0$ (N-2)/2 and $h \equiv 0$, then $u_h(x)/|x|$ and $|x|^{\theta+1}u_h^q$ belong to $L^2(\Omega)$, $u_h \in H^1_0(\Omega)$ and, for every $\varphi \in H_0^1(\Omega)$,

$$\int_{\Omega} \nabla u_h \cdot \nabla \varphi \, dx - \int_{\Omega} \frac{\lambda}{|x|^2} u_h \, \varphi \, dx + \int_{\Omega} |x|^{\theta} u_h^q \, \varphi \, dx = 0.$$
(1.15)

- (2) Assume Case (\mathcal{M}_1) or Case (\mathcal{N}) . If $h \neq 0$ on $\partial\Omega$, then problem (1.14) has a unique solution u_h .
- (3) If $h \equiv 0$ on $\partial\Omega$, then (1.14) has no solutions in Case (\mathcal{M}_1) and Case (\mathcal{N}) .
- (4) Assume Case (\mathcal{M}_2). Then, (1.14) has infinitely many solutions: for every $\gamma \in (0, \infty]$ (also for $\gamma = 0$ when $h \not\equiv 0$ on $\partial \Omega$), problem (1.14), subject to

$$\lim_{|x|\to 0} \frac{u(x)}{\Phi_{\lambda}^+(x)} = \gamma \tag{1.16}$$

has a unique solution $u_h^{(\gamma)}$. Moreover, for $\gamma = \infty$, the solution $u_h^{(\gamma)}$ satisfies

$$\lim_{|x| \to 0} \frac{u_h^{(\gamma)}(x)}{U_0(x)} = 1.$$

- (a) If $h \neq 0$ on $\partial\Omega$, then $\{u_h^{(\gamma)}: 0 \leq \gamma \leq \infty\}$ is the set of all solutions of problem (1.14) and for $\gamma = 0$ we have $\lim_{|x|\to 0} |x|^{p_-} u_h^{(\gamma)}(x) \in (0,\infty)$. (b) If h = 0 on $\partial\Omega$, then all solutions of (1.14) are $\{u_h^{(\gamma)}: 0 < \gamma \leq \infty\}$.

We point out that under the hypotheses of Theorem 1.3, the behavior near zero for the unique solution u_h of (1.14) is provided by Theorem 1.2 in Cases (\mathcal{U}) and (\mathcal{M}_1) and by Theorem 2.1 in Case (\mathcal{N}). The assertions (2) and (4) in Theorem 1.3 extend corresponding results in [13] for $\Omega = B_1(0)$. The novelty in Theorem 1.3 is given by the conclusions in (1) and (3).

In contrast to Case (\mathcal{U}) , the problem (1.14) with u = 0 on $\partial\Omega$ has no solutions in Case (\mathcal{M}_1) . This can be shown using the Hardy inequality (see Remark 6.2) or by another argument relying on Theorem 1.2. Indeed, suppose that u is a solution of (1.14) with u = 0 on $\partial\Omega$. Then, $\lim_{|x|\to 0} |x|^{p_-} u(x) = 0$ in Case (\mathcal{M}_1) since $\Theta < p_-$. Hence, for every $\varepsilon > 0$, we have $u(x) \le \varepsilon |x|^{-p_-}$ for |x| > 0 close to zero and for every $x \in \partial\Omega$ so that $0 < u(x) \le \varepsilon |x|^{-p_-}$ for every $x \in \Omega \setminus \{0\}$ in view of Lemma 4.1. By letting $\varepsilon \to 0$, we arrive at $u \equiv 0$ in $\Omega \setminus \{0\}$, which is a contradiction. This argument can be easily adapted in Case (\mathcal{N}) to establish the non-existence of solutions to (1.14) with h = 0.

For $\theta > -2$ in Case (\mathcal{U}) and h = 0, the existence and uniqueness claim in Theorem 1.3 was proved differently by Wei and Du [42, Proposition 2.5]. Their analysis relied on rough estimates [42, Lemma 2.4]: there exist positive constants C_1, C_2, r_0 such that every solution u of (1.2) satisfies

$$C_1|x|^{-\Theta} \le u(x) \le C_2|x|^{-\Theta}$$
 for all $0 < |x| < r_0$. (1.17)

Then, arguing by contradiction, any solution of (1.14) with h = 0 was shown to coincide with its minimal solution w via the strong maximum principle and a convexity trick of Marcus and Véron [30, 31]. The condition $\lambda > \lambda_H$ was essential in gaining the minimal solution w as the limit $\delta \to 0^+$ of the unique solution u_{δ} to (1.2) in $\Omega^{\delta} := \Omega \setminus \overline{B_{\delta}(0)}$, subject to u = 0 on $\partial \Omega^{\delta}$. It was shown that $\liminf_{|x|\to 0} w(x)/U_0(x) > 0$ by a comparison with the unique solution of (1.2) in a suitable annular domain with zero Dirichlet boundary condition. The first inequality of (1.17) shows that every solution of (1.2) blows-up at zero by the assumption $\theta > -2$ in Case (\mathcal{U}). The second inequality in (1.17) was derived for the maximal solution U of (1.2) satisfying $U = \infty$ on $\partial \Omega$, which was constructed in [42] as the limit ($\delta \to 0^+$) of the unique solution U_{δ} to (1.2) on the approximate domain Ω^{δ} with boundary blow-up.

In Theorem 1.3 we show that Case (\mathcal{U}) is the maximal range for which (1.14) with h = 0 on $\partial\Omega$ has a unique solution. Hence, not only we give an alternative proof of [42, Proposition 2.5] for $\theta > -2$ in Case (\mathcal{U}) but also extend its existence and uniqueness conclusion to the entire Case (\mathcal{U}) .

We now give some ideas behind our proof of Theorem 1.3. As a byproduct of Theorem 1.2 in Cases (\mathcal{U}) and (\mathcal{M}_1) (and of Theorem 2.1 in Case (\mathcal{N})), jointly with Lemma 4.1, we find that (1.14) has at most a solution. We obtain a non-negative solution u_h of (1.14) as the limit when $k \to \infty$ of the unique positive solution $u_{h,k}$ of (1.2) in $\Omega \setminus \overline{B_{1/k}(0)}$, subject to u = h on $\partial\Omega$ and $u = C |x|^{-\Theta}$ on $\partial B_{1/k}(0)$, where C > 0 is a large constant. When $h \neq 0$ on $\partial\Omega$ in Cases (\mathcal{M}_1) and (\mathcal{N}), the positivity of u_h in Ω follows from the strong maximum principle. When h = 0in Cases (\mathcal{U}) and (\mathcal{M}_2), we prove that $u_h > 0$ in Ω by showing that $u_{h,k}(x) \geq z_{\delta}(x)$ for every $1/k \leq |x| \leq \delta$ and every $k \geq k_0$ large enough, where z_{δ} is defined by

$$z_{\delta}(x) := c U_0(x) \left[1 - \left(\frac{|x|}{\delta}\right)^{\alpha} \right]^{\frac{1}{\sqrt{\alpha}}} \quad \text{for every } 0 < |x| \le \delta.$$
 (1.18)

(Here, like for w_{δ} in (1.11), we fix $\alpha > 0$ small, depending only on N, q, θ and λ .) By applying the Kelvin transform to the sub-solution w_{δ} of (1.2) in $\mathbb{R}^N \setminus \overline{B_{\delta}(0)}$ for Cases (\mathcal{U}) and (\mathcal{M}_1), we obtain that z_{δ} is a sub-solution of (1.2) in $B_{\delta}(0) \setminus \{0\}$ for Cases (\mathcal{U}) and (\mathcal{M}_2).

In Case (\mathcal{M}_2) , the solution u_h constructed above for problem (1.14) is the maximal one since it satisfies $\liminf_{|x|\to 0} u_h(x)/U_0(x) > 0$, which yields $\lim_{|x|\to 0} u_h(x)/U_0(x) = 1$ via Proposition 5.2. Case (\mathcal{M}_2) is the only one when (1.14) has infinitely many solutions (see Section 6 for details).

We next return to (1.2) with $\Omega = \mathbb{R}^N$. Taking Case (\mathcal{M}_1) separately from Case (\mathcal{M}_2) , we determine in Theorem 1.4 all solutions of (1.2) in $\mathbb{R}^N \setminus \{0\}$, together with their behavior near zero and at infinity. If it were to exist, such a solution would satisfy at zero the limit behavior given by Theorem 2.1, whereas at infinity the precise behavior listed in Theorem 2.2.

Theorem 1.4 (Multiplicity, Cases (\mathcal{M}_1) and (\mathcal{M}_2)). Let $\Omega = \mathbb{R}^N$.

- Let Case (M₂) hold. For every γ ∈ (0,∞), equation (1.2), subject to (1.16), has a unique solution u_γ. All solutions of problem (1.2) satisfy (1.13) and are radially symmetric, being given by U₀ and {u_γ : γ ∈ (0,∞)}. In addition, we have u_γ ≤ u_{γ'} ≤ U₀ in ℝ^N \ {0} for every 0 < γ < γ' < ∞ and U₀(x) = lim_{γ→∞} u_γ(x) for each x ∈ ℝ^N \ {0}.
 Let Case (M₂) hold. For every q ∈ (0,∞) equation (1.2), subject to (1.16), has a unique solution to (1.2).
- (2) Let Case (\mathcal{M}_1) hold. For every $\gamma \in (0, \infty)$, equation (1.2), subject to

$$\lim_{|x| \to \infty} \frac{|x|^{N-2} u(x)}{\Phi_{\lambda}^{+}(1/|x|)} = \gamma$$
(1.19)

has a unique solution, say U_{γ} . All solutions of problem (1.2) satisfy (1.9) and are radially symmetric, being given by U_0 and $\{U_{\gamma}: \gamma \in (0, \infty)\}$.

By the Kelvin transform in (2.7), the claims of Theorem 1.4 in Case (\mathcal{M}_1) follow from those of Case (\mathcal{M}_2) , the latter being treated in Proposition 7.1. Theorem 1.4 uncovers an unexpected feature: there are no solutions of (1.2) in $\mathbb{R}^N \setminus \{0\}$ satisfying $\lim_{|x|\to 0} |x|^{p-} u(x) \in (0,\infty)$ for Case (\mathcal{M}_2) and, hence, no solutions exist satisfying $\lim_{|x|\to\infty} |x|^{p+} u(x) \in (0,\infty)$ for Case (\mathcal{M}_1) .

We remark that in Case (\mathcal{M}_2) (respectively, Case (\mathcal{M}_1)) of Theorem 1.4, we can obtain the solutions u_{γ} (respectively, U_{γ}) with $\gamma \in (0, \infty)$ from the solution corresponding to $\gamma = 1$. We next make this point clear. Given $\mu > 0$, let $T_{\mu} : C^1(\mathbb{R}^N \setminus \{0\}) \to C^1(\mathbb{R}^N \setminus \{0\})$ be the operator defined by

$$T_{\mu}(u)(x) := \mu^{\Theta} u(\mu x) \text{ for every } x \in \mathbb{R}^N \setminus \{0\}.$$

Observe that whenever U_0 in (1.5) is well-defined such as in Cases (\mathcal{M}_1) and (\mathcal{M}_2) , we have $T_{\mu}(U_0) = U_0$. Moreover, the transformation T_{μ} sends a solution of (1.2) with $\Omega = \mathbb{R}^N$ into a solution of the same equation.

Let $\Omega = \mathbb{R}^N$ and Case (\mathcal{M}_2) hold. By Theorem 1.4, there exists a unique solution $u_{1,\theta}$ of problem (1.2), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = 1$. Moreover, $u_{1,\theta}$ is radially symmetric and satisfies $\lim_{|x|\to\infty} u_{1,\theta}(x)/U_0(x) = 1$. Then, all solutions of (1.2) are given by U_0 and $\{T_{\mu}(u_{1,\theta}): 0 < \mu < \infty\}$. (The solution u_{γ} of (1.2), subject to (1.16), corresponds to $T_{\mu}(u_{1,\theta})$ with $\mu = \gamma^{1/(\Theta - p_+)}$.)

If Case (\mathcal{M}_1) holds instead of Case (\mathcal{M}_2) , then all solutions of (1.2) are given by U_0 and $\{T_{\mu}(U_{1,\theta}): 0 < \mu < \infty\}$, where $U_{1,\theta}$ is the Kelvin transform of $u_{1,\widehat{\theta}}$ with $\widehat{\theta} = (N-2)q - (N+2+\theta)$, namely, $U_{1,\theta}(x) = |x|^{2-N} u_{1,\widehat{\theta}}(x/|x|^2)$. (The solution U_{γ} of (1.2), subject to (1.19), is $T_{\mu}(U_{1,\theta})$ with $\mu = \gamma^{1/(\Theta-p_-)}$.)

We next illustrate explicitly the findings of Theorem 1.4.

Example. Fix q > 1 and $-\infty < \lambda < \lambda_H$.

(i) In Case (\mathcal{M}_2) if $\theta = \theta_+ + 4\sqrt{\lambda_H - \lambda}$, then $U_0 \cup \{u_{\mu,\theta} : 0 < \mu < \infty\}$ represent all solutions of (1.2) in $\mathbb{R}^N \setminus \{0\}$, where we define

$$u_{\mu,\theta}(x) := |x|^{-p_+} \left(\mu^{-2\sqrt{\lambda_H - \lambda}} + [\ell(\theta)]^{-\frac{1}{2}} |x|^{2\sqrt{\lambda_H - \lambda}} \right)^{-\frac{2}{q-1}} \text{ for } x \in \mathbb{R}^N \setminus \{0\}.$$

(ii) In Case (\mathcal{M}_1) if $\theta = \theta_- - 4\sqrt{\lambda_H - \lambda}$, then $U_0 \cup \{U_{\mu,\theta} : 0 < \mu < \infty\}$ is the set of all solutions of (1.2) in $\mathbb{R}^N \setminus \{0\}$, where we define

$$U_{\mu,\theta}(x) := |x|^{-p_-} \left(\mu^{2\sqrt{\lambda_H - \lambda}} + [\ell(\theta)]^{-\frac{1}{2}} |x|^{-2\sqrt{\lambda_H - \lambda}} \right)^{-\frac{2}{q-1}} \text{ for } x \in \mathbb{R}^N \setminus \{0\}.$$

In Case (\mathcal{N}) , we obtain that there are no solutions of (1.2) in $\mathbb{R}^N \setminus \{0\}$.

Theorem 1.5 (Non-existence, Case (\mathcal{N})). Problem (1.2) with $\Omega = \mathbb{R}^N$ has no solutions in Case (\mathcal{N}) .

This non-existence result is somehow startling and it ensues essentially from $\Omega = \mathbb{R}^N$ in (1.2). Theorem 1.3 shows that (1.2) in $B_1(0) \setminus \{0\}$ admits solutions exhibiting near zero each of the behaviors prescribed by Theorem 2.1. Yet, surprisingly, in Case (\mathcal{N}) none of these local solutions can be extended as a solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$. Were it to exist, a solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$ would have the limit behavior near zero and at infinity given in Table 1. Using essentially such precise asymptotics in Case (\mathcal{N}), we are able to rule out the existence of solutions of (1.2) for $\Omega = \mathbb{R}^N$.

TABLE 1. Possible profiles in Case (\mathcal{N})

$\mathbf{Case}\ (\mathcal{N})$	behavior near zero in	behavior at infinity in
$\theta < \theta < \theta +$	(2.1)	(2.4)
$\theta = \theta < \theta_+$	(2.2)	(2.4)
$\theta = \theta_+ > \theta$	(2.1)	(2.5)
$\theta=\theta=\theta_+$	(2.3)	(2.6)

1.3. Applications to weighted divergence-form equations. Here, we consider a related problem that can be solved using our method and results from Section 1.2. For $N \ge 3$, we study the nonlinear elliptic problem

$$\begin{cases} \operatorname{div}(|x|^{-2a}\nabla v) + d |x|^{-2(1+a)} v = |x|^{b} v^{q} & \operatorname{in} \mathbb{R}^{N} \setminus \{0\}, \\ v > 0 & \operatorname{in} \mathbb{R}^{N} \setminus \{0\}, \end{cases}$$
(1.20)

where $a, b, d, q \in \mathbb{R}$, in the super-linear case q > 1.

Before stating our main result on (1.20), we indicate what is known in the literature. For b = d = 0 and -1 < a < (N-2)/2, the influence of the weight $|x|^{-2a}$ in the divergence-form elliptic operator on the existence and local behavior near zero of the singular solutions of (1.20) in $B_1(0) \setminus \{0\}$ follows from [4]: there exist positive solutions satisfying $\lim_{|x|\to 0} |x|^{N-2-2a} v_{\gamma}(x) = \gamma$ for some $\gamma \in (0, \infty]$ if and only if 1 < q < N/(N-2-2a); in turn, if $q \ge N/(N-2-2a)$, then every solution of (1.20) in $B_1(0) \setminus \{0\}$ can be extended as a positive continuous solution of (1.20) in $B_1(0) \setminus \{0\}$ can be extended as a positive continuous solution of (1.20) in $B_1(0) \setminus \{0\}$ recent generalizations of these local existence and classification results to weighted quasilinear elliptic equations, see [10, 35].

Returning to (1.20) with d = 0, we point out that the local behavior near zero has not been fully elucidated given that in the above-mentioned works, the parameters a and b are restricted to specific ranges (e.g., $a \leq (N-2)/2$ and b > -N), the focus being on the existence of singular solutions near zero (see, for example, Remark 1.1 in [35]). Unfortunately, this limits our understanding of the behavior at infinity for the solutions of (1.20); if v is a solution of (1.20), then by applying a generalized Kelvin transform, namely,

$$\widehat{v}(x) := |x|^{2-N+2a} v(x/|x|^2), \tag{1.21}$$

it is readily seen that \hat{v} satisfies (1.20) but with b replaced by

$$\widehat{b} := (N - 2 - 2a) q - (N + 2a + b + 2).$$
(1.22)

Using our main results regarding problem (1.2) with $\Omega = \mathbb{R}^N$, for every $a, b, d \in \mathbb{R}$ and q > 1, we obtain in Theorem 1.6 a sharp criterion for the existence of solutions of (1.20), together with their exact profile near zero and at infinity. As a consequence, we derive that whenever they exist, *all* solutions of (1.20) are radially symmetric. For ease of reference, we define

$$\sigma := \frac{2a+b+2}{q-1}, \quad \rho := a - \frac{N-2}{2} \quad \text{and} \quad \ell := (\sigma+\rho)^2 - \rho^2 + d. \tag{1.23}$$

We next state our main result concerning (1.20).

Theorem 1.6. Problem (1.20) has a solution if and only if $\ell > 0$.

(i) If $d > \rho^2$, then problem (1.20) has a unique solution given by

$$v_0(x) := \ell^{\frac{1}{q-1}} |x|^{-\sigma} \quad \text{for every } x \in \mathbb{R}^N \setminus \{0\}.$$

$$(1.24)$$

(ii) If $(\sigma + \rho)^2 > \rho^2 - d \ge 0$ (for $\sigma \ne -\rho$), then (1.20) has infinitely many solutions, all radially symmetric and their total set is $v_0 \cup \{v_\gamma : \gamma \in (0,\infty)\}$. For every $\gamma \in (0,\infty)$, we denote by v_γ the unique solution of (1.20) that satisfies the limit behavior near zero and at infinity given in Table 2.

TABLE 2. Precise asymptotics for v_{γ}

Case	Criterion for existence	Behavior as $ x \rightarrow 0$	Behavior as $ x \to \infty$
(M_{11})	$d < \rho^2, \ \sigma + \rho < -\sqrt{\rho^2 - d}$	$\frac{v_{\gamma}(x)}{v_0(x)} \to 1$	$\frac{v_{\gamma}(x)}{ x ^{\rho+\sqrt{\rho^2-d}}} \to \gamma$
(M_{21})	$d < \rho^2, \ \sigma + \rho > \sqrt{\rho^2 - d}$	$\frac{v_{\gamma}(x)}{ x ^{\rho-\sqrt{\rho^2-d}}} \to \gamma$	$\frac{v_{\gamma}(x)}{v_0(x)} \to 1$
(M_{12})	$d = \rho^2 \ and \ \sigma < -\rho$	$rac{v_{\gamma}(x)}{v_0(x)} ightarrow 1$	$\frac{v_{\gamma}(x)}{ x ^{\rho} \log x } \to \gamma$
(M_{22})	$d = \rho^2 \ and \ \sigma > -\rho$	$\frac{v_{\gamma}(x)}{ x ^{\rho}\log(1/ x)} \to \gamma$	$\frac{v_{\gamma}(x)}{v_0(x)} \to 1$

Theorem 1.6 appears here for the first time except for a = b = d = 0.

We note the connection between various cases displayed in Table 2. For a solution v of (1.20) in Case (M_{11}) (respectively, (M_{12})), its generalized Kelvin transform \hat{v} in (1.21) is a solution of (1.20) (with $b = \hat{b}$ in (1.22)) in Case (M_{21}) (respectively, (M_{22})). (Indeed, if we denote by $\hat{\sigma}$ the value we obtain for σ when b is replaced by \hat{b} , then $\hat{\sigma} = -2\rho - \sigma$ and thus the condition $\sigma + \rho < -\sqrt{\rho^2 - d}$ in (M_{11}) translates as $\hat{\sigma} + \rho > \sqrt{\rho^2 - d}$ in (M_{21}) .)

To obtain Theorem 1.6, for a solution v of (1.20), we use the transformation

$$u(x) := |x|^{-a} v(x). \tag{1.25}$$

Then, a direct calculation shows that u is a positive solution of

$$-\Delta u - \frac{\lambda}{|x|^2} u + |x|^{\theta} u^q = 0 \quad \text{in } \mathbb{R}^N \setminus \{0\},$$
(1.26)

where λ and θ are here given by

 $\lambda := d + a \left(N - 2 - a \right) \quad \text{and} \quad \theta := a \left(1 + q \right) + b.$

Hence, Theorem 1.6 follows by applying Theorems 1.1, 1.4 and 1.5 for problem (1.26), then using the transformation in (1.25).

Remark 1.7. Due to (1.25), we can put problem (1.20) in the same framework as in (1.2) and reformulate all our findings for (1.14) in Theorem 1.3 to obtain corresponding conclusions for (1.20) in $\Omega \setminus \{0\}$, subject to $u = h \ge 0$ on $\partial\Omega$, where $\Omega \subset \mathbb{R}^N$ is a smooth bounded domain containing zero and $h \in C(\partial\Omega)$. We leave these statements to the reader, who would then be able to get a full picture of all solutions of (1.20) whether considered locally or globally. In special cases, problems of the type (1.20) but with an opposite sign in the right-hand side of (1.20) have been studied extensively by many authors motivated by applications to Riemannian geometry, as well as by various connections with the Caffarelli–Kohn–Nirenberg inequalities (e.g., [8,9,19,29] and references therein); their treatment is based on variational or moving plane methods or uses the finite dimensional reduction of Lyapunov–Schmidt.

In this paper, we follow a different approach since the sign in the right-hand side of (1.20) does not allow us to use moving plane techniques, whereas variational methods cannot be employed here because of certain types of singularities that appear near zero for the solutions of (1.20).

Structure of the paper. In Theorem 2.1 of Section 2, we recall from [13] all the profiles near zero for the solutions of (1.2) with $\Omega = \Omega_0$. Based on this result and using the Kelvin transform and Theorem 1.2, we deduce in Theorem 2.2 the asymptotic behavior at infinity for the solutions of (1.2) with $\Omega = \Omega_{\infty}$. In Section 3 we check that the functions w_{δ} and z_{δ} given in (1.11) and (1.18), respectively are sub-solutions of (1.2) on suitable domains. In Section 4 we include basic ingredients that will be often used in the sequel such as the comparison principle in Lemma 4.1 and the *a priori* estimates in Lemma 4.2. In Section 5 we prove Theorem 1.1 and Theorem 1.2. In Section 6 we establish the assertions of Theorem 1.3 on the existence of solutions of (1.14). We dedicate Section 7 to the proof of Theorem 1.4. The claim of Theorem 1.5 is proved in Section 8. We conclude the paper with comments and remarks in Section 9.

2. Asymptotic behavior near zero / at infinity

For $\lambda \leq \lambda_H$ and $\theta > -2$ the sharp local behavior near zero and existence of solutions of (1.2) in $B_1(0) \setminus \{0\}$ is established in [13], presenting a great diversity, which is recalled in Theorem 2.1. The study in [13] concerned more general nonlinear elliptic equations than (1.2) by invoking regularly varying functions (the weight $|x|^{\theta}$ in (1.2) was replaced by a regularly varying function at zero with index $\theta > -2$). Some results in [13] such as those in Chapter 3.1 and the *a priori* estimates of Lemma 4.1 when applied to our equation (1.2) carry over beyond the range $\theta > -2$ (see Lemma 4.2 in Section 4).

Theorem 2.1 (See Chapter 7 in [13]). Let $\Omega = \Omega_0$, $\theta > -2$ and u be any solution of problem (1.2).

- (i) If Case (\mathcal{M}_1) holds, then u satisfies (1.9);
- (ii) If Case (\mathcal{M}_2) holds, then exactly one of the following occurs:
 - (A) $\lim_{|x|\to 0} |x|^{p_-} u(x) \in (0,\infty);$
 - (B) There exists $\gamma \in (0, \infty)$ such that $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$;
 - (C) u satisfies (1.9).
- (iii) Assume Case (\mathcal{N}). Then, $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = 0$ and we have (\mathcal{N}_1) If $\theta_- < \theta \le \theta_+$ for $\lambda < \lambda_H$, then

$$\lim_{|x| \to 0} |x|^{p_{-}} u(x) \in (0, \infty);$$
(2.1)

 (\mathcal{N}_2) If $\theta = \theta_- < \theta_+$ for $\lambda < \lambda_H$, then u satisfies

$$\lim_{|x|\to 0} |x|^{p_{-}} \left(\log \frac{1}{|x|} \right)^{\frac{1}{q-1}} u(x) = \left(\frac{N-2-2p_{-}}{q-1} \right)^{\frac{1}{q-1}};$$
(2.2)

 (\mathcal{N}_3) If $\theta = \theta_- = \theta_+$ for $\lambda = \lambda_H$, then u satisfies

$$\lim_{|x|\to 0} |x|^{\frac{N-2}{2}} \left(\log \frac{1}{|x|} \right)^{\frac{2}{q-1}} u(x) = \left[\frac{2(q+1)}{(q-1)^2} \right]^{\frac{1}{q-1}}.$$
(2.3)

We remark that the condition $\theta > -2$ in Theorem 2.1 can be removed (relevant for Case (\mathcal{M}_1) and items (\mathcal{N}_1) and (\mathcal{N}_2) in (iii)) and the conclusions extended according to the specified case. We indicate why in Case (\mathcal{M}_1) the condition $\theta > -2$ is not needed to reach (1.9). The idea in [13] is to reduce the proof of (1.9) to the case of radially symmetric solutions u(r) = u(|x|) in $B_1(0) \setminus \{0\}$ and for these to use a suitable change of variable:

$$y(s) = u(r)/\Phi_{\lambda}^{-}(r)$$
 with $s = \Phi_{\lambda}^{+}(r)/\Phi_{\lambda}^{-}(r)$.

In Case (\mathcal{M}_1) , the *a priori* estimates in Lemma 4.2 (see Section 4) imply that $\lim_{r\to 0^+} u(r)/\Phi_{\lambda}^+(r) = 0$. Since $\lim_{\tau\to 0} \int_{\tau}^{1} r^{1+\theta-(q-1)p_-} dr = \infty$ if $\lambda < \lambda_H$ and $\lim_{\tau\to 0} \int_{\tau}^{1/2} r^{\theta+[N-q(N-2)]/2} \log(1/r) dr = \infty$ if $\lambda = \lambda_H$, then Theorem 1.1 in Taliaferro [36] gives that any two positive solutions of the differential equation satisfied by y are asymptotically equivalent at ∞ . This means that every positive radial solution u of (1.2) in $B_1(0) \setminus \{0\}$ satisfies $\lim_{r\to 0^+} u(r)/U_0(r) = 1$. The ingredients used to reduce to the radial case work for every $\theta \in \mathbb{R}$, see Lemma 4.2, Lemma 4.4 and Remark 4.5.

The claim of Theorem 2.1 in Case (\mathcal{N}_1) holds for every $\theta_- < \theta \leq \theta_+$ with the same proof as for max $\{-2, \theta_-\} < \theta \leq \theta_+$. Similarly, with the methods in [13], the assertion of Case (\mathcal{N}_2) , which was proved for $\theta = \theta_-$ and $0 < \lambda < \lambda_H$, remains valid for $\lambda \leq 0$.

From Theorem 1.2 and Theorem 2.1, we gain full understanding of the limit behavior near zero for all solutions of (1.2) for every $\theta, \lambda \in \mathbb{R}$ and q > 1. This and the Kelvin transform allow us to classify the local behavior at infinity for every solution of (1.2) as follows.

Theorem 2.2 (Classification of the behavior at ∞). Suppose that u is an arbitrary solution of (1.2) with $\Omega = \Omega_{\infty}$.

- •: In Case (\mathcal{U}) and Case (\mathcal{M}_2) , we have (1.13).
- •: In Case (\mathcal{M}_1) , exactly one of the following behaviors occurs:
 - (**D**) $\lim_{|x|\to\infty} |x|^{p_+} u(x) \in (0,\infty);$
 - (E) There exists $\gamma \in (0,\infty)$ such that $\lim_{|x|\to\infty} |x|^{N-2} u(x)/\Phi_{\lambda}^+(1/|x|) = \gamma;$
 - (**F**) u satisfies (1.13).
- •: In Case (\mathcal{N}) , we distinguish three situations:

(1) If $\theta_{-} \leq \theta < \theta_{+}$, then

$$\lim_{|x| \to \infty} |x|^{p_+} u(x) \in (0, \infty);$$
(2.4)

(2) If $\theta = \theta_+$ and $\lambda < \lambda_H$, then u satisfies

$$\lim_{|x| \to \infty} |x|^{p_+} (\log |x|)^{\frac{1}{q-1}} u(x) = \left(\frac{N-2-2p_-}{q-1}\right)^{\frac{1}{q-1}};$$
(2.5)

(3) If $\theta = \theta_+$ and $\lambda = \lambda_H$, then

$$\lim_{|x| \to \infty} |x|^{\frac{N-2}{2}} \left(\log |x| \right)^{\frac{2}{q-1}} u(x) = \left[\frac{2(q+1)}{(q-1)^2} \right]^{\frac{1}{q-1}}.$$
(2.6)

The existence of all the profiles at infinity prescribed by Theorem 2.2 follows from Theorem 1.3 and the Kelvin transform.

The Kelvin transform. Let $\Omega = \mathbb{R}^N$ with $N \geq 3$. For a solution u of (1.2), let u_* be its Kelvin transform with respect to the unit sphere in \mathbb{R}^N :

$$u_*(x) := |x|^{2-N} u(x/|x|^2) \quad \text{for } x \in \mathbb{R}^N \setminus \{0\}.$$
(2.7)

Since $\Delta u_*(x) = |x|^{-N-2} (\Delta u) (x/|x|^2)$, we obtain that u_* satisfies an equation of the same type as u, where θ is replaced by $\hat{\theta} := (N-2) q - (N+2+\theta)$. In other words, we have

$$-\Delta u_* - \frac{\lambda}{|x|^2} u_* + |x|^{\widehat{\theta}} u_*^q = 0 \quad \text{in } \mathbb{R}^N \setminus \{0\}.$$

$$(2.8)$$

The behavior of u_* near zero (respectively, at infinity) is obtained from the behavior of u at infinitely (respectively, near zero) by using (2.7). For such conversions, it is useful to keep in mind that

$$\widehat{\Theta} := \frac{\theta + 2}{q - 1} = N - 2 - \Theta \quad \text{and} \quad \widehat{\ell} := \widehat{\Theta}^2 - (N - 2)\,\widehat{\Theta} + \lambda = \ell.$$
(2.9)

We see that if $\hat{\theta} \leq -2$, then $\theta > -2$ and similarly, $\theta \leq -2$ implies that $\hat{\theta} > -2$ since q > 1. In addition, if $\lambda \leq \lambda_H$, we have $\hat{\theta} = \theta_+ + \theta_- - \theta$ using θ_\pm in (1.3); thus, $\hat{\theta} < \theta_-$ is equivalent to $\theta > \theta_+$, whereas $\hat{\theta} > \theta_+$ if and only if $\theta < \theta_-$.

What this means is that in Case (\mathcal{U}) (Case (\mathcal{M}_1) and Case (\mathcal{M}_2) , respectively) if u is a solution of (1.2), then its behavior at zero leads (through its Kelvin transform u_*) to knowledge of the behavior at infinity for some other solution of (1.2) in Case (\mathcal{U}) (Case (\mathcal{M}_2) and Case (\mathcal{M}_1) , respectively). Then, Theorem 1.2 implies in Case (\mathcal{U}) and Case (\mathcal{M}_2) that every solution u of (1.2) satisfies a unique behavior at infinity given by (1.13) using the Kelvin transform in (2.7) and (2.9).

3. Construction of explicit "rough" sub-solutions

In Lemma 3.1 we proceed with the explicit construction and verification of the "rough" subsolutions w_{δ} for (1.2) on exterior domains in Cases (\mathcal{U}) and (\mathcal{M}_1). This will find application in the proof of Theorem 1.2 via Corollary 3.2. In addition, through the Kelvin transform, we immediately acquire corresponding sub-solutions z_{δ} of (1.2) for $0 < |x| \le \delta$ in Cases (\mathcal{U}) and (\mathcal{M}_2), which will be used in the proof of Theorem 1.3.

Lemma 3.1. In Case (\mathcal{U}) and Case (\mathcal{M}_1), for every $\alpha > 0$ small, depending on N, q, θ and λ , there exists $c_{\alpha} > 0$ such that for every constant $c \in (0, c_{\alpha})$ and all $\delta > 0$, the function w_{δ} given by

$$w_{\delta}(x) := c U_0(x) \left[1 - \left(\frac{\delta}{|x|}\right)^{\alpha} \right]^{\frac{1}{\sqrt{\alpha}}} \quad for \ every \ |x| \ge \delta \tag{3.1}$$

satisfies the following inequality

$$-\mathbb{L}_{\lambda}(w_{\delta}) + |x|^{\theta} (w_{\delta})^{q} \leq 0 \quad \text{for every } |x| > \delta.$$

$$(3.2)$$

Proof. Assume Case (\mathcal{U}) or Case (\mathcal{M}_1). Recall that $\ell > 0$. For every $\alpha > 0$, we use the notation

$$A_{\alpha} := 1 - \frac{\sqrt{\alpha}}{\ell} \left(N - 2 - 2\Theta - \sqrt{\alpha} \right)$$

$$B_{\alpha} := -2 + \frac{\sqrt{\alpha}}{\ell} \left(N - 2 - 2\Theta - \alpha \right).$$
(3.3)

Using the definition of w_{δ} in (3.1), for every $|x| > \delta$, we obtain that

$$\mathbb{L}_{\lambda}(w_{\delta}) = c \,\ell^{\frac{q}{q-1}} |x|^{-\Theta-2} \left[1 - \left(\frac{\delta}{|x|}\right)^{\alpha} \right]^{\frac{1}{\sqrt{\alpha}}-2} \left[A_{\alpha} \left(\frac{\delta}{|x|}\right)^{2\alpha} + B_{\alpha} \left(\frac{\delta}{|x|}\right)^{\alpha} + 1 \right]$$

as well as

$$|x|^{\theta}(w_{\delta}(x))^{q} = c^{q} \ell^{\frac{q}{q-1}} |x|^{-\Theta-2} \left[1 - \left(\frac{\delta}{|x|}\right)^{\alpha}\right]^{\frac{q}{\sqrt{\alpha}}}.$$

For every $t \in (0, 1)$, we define

$$h_{\alpha}(t) := (1-t)^{-\frac{1}{\sqrt{\alpha}}(q-1)-2} \left(A_{\alpha} t^{2} + B_{\alpha} t + 1 \right).$$

If $t = (\delta/|x|)^{\alpha}$, then the inequality in (3.2) is equivalent to

$$h_{\alpha}(t) \ge c^{q-1} \quad \text{for every } t \in (0,1). \tag{3.4}$$

We prove below that we can choose $\alpha \in (0,1)$ small, depending only on N, q, θ and λ , such that

$$\inf_{t \in (0,1)} h_{\alpha}(t) > 0. \tag{3.5}$$

Let $\alpha \in (0,1)$ be small such that $A_{\alpha} > 0$. Observe that

$$A_{\alpha} + B_{\alpha} + 1 = \frac{\alpha}{\ell} \left(1 - \sqrt{\alpha} \right) > 0.$$
(3.6)

By a simple computation, using (3.3), we find that

$$B_{\alpha}^{2} - 4A_{\alpha} = \frac{4\alpha}{\ell^{2}} \left\{ \lambda_{H} - \lambda + \ell\sqrt{\alpha} + \frac{\alpha}{4} \left[\alpha - 2\left(N - 2 - 2\Theta \right) \right] \right\}.$$

To prove (3.5), we analyze Case (\mathcal{U}) separately from Case (\mathcal{M}_1) .

- (\mathcal{U}) Let $\lambda > \lambda_H$ and $\theta \in \mathbb{R}$. Then, we have $B_{\alpha}^2 4A_{\alpha} < 0$ by choosing $\alpha > 0$ small enough. Hence, $A_{\alpha} t^2 + B_{\alpha} t + 1 > 0$ for every $t \in \mathbb{R}$. (\mathcal{M}_1) Let $\lambda \leq \lambda_H$ and $\theta < \theta_-$. Then for $\alpha > 0$ small enough, we have that $B_{\alpha}^2 - 4A_{\alpha} > 0$
- (\mathcal{M}_1) Let $\lambda \leq \lambda_H$ and $\theta < \theta_-$. Then for $\alpha > 0$ small enough, we have that $B_{\alpha}^2 4A_{\alpha} > 0$ and, hence, the quadratic equation $A_{\alpha} t^2 + B_{\alpha} t + 1 = 0$ has two distinct roots, say $t_1(\alpha)$ and $t_2(\alpha)$. Since $\theta < \theta_-$ is equivalent to $\Theta < p_-$, from $p_- \leq (N-2)/2$, we obtain that $N-2-2\Theta > 0$. Hence, we have $t_1(\alpha) t_2(\alpha) = 1/A_{\alpha} > 1$ for $\alpha \in (0,1)$ small enough. Then, both roots $t_1(\alpha)$ and $t_2(\alpha)$ are greater than 1 in view of (3.6). Hence, we have

 $A_{\alpha} t^2 + B_{\alpha} t + 1 > 0 \quad \text{for every } t \in [0, 1].$ (3.7)

Since (3.7) holds for Case (\mathcal{U}) and Case (\mathcal{M}_1), using that $(1-t)^{-\frac{1}{\sqrt{\alpha}}(q-1)-2} \geq 1$ for every $t \in [0, 1)$, we deduce (3.5).

We define $c_{\alpha} = \left(\inf_{t \in (0,1)} h_{\alpha}(t)\right)^{1/(q-1)} > 0$. Then, for every $0 < c < c_{\alpha}$, we obtain (3.4). This ends the proof of Lemma 3.1.

Corollary 3.2. Let $\Omega = \Omega_0$. In Case (\mathcal{U}) and Case (\mathcal{M}_1), every solution u of problem (1.2) satisfies

$$\liminf_{|x| \to 0} \frac{u(x)}{U_0(x)} > 0.$$
(3.8)

Proof. Let $r_0 \in (0,1)$ be such that $\overline{B_{r_0}(0)} \subset \Omega$. Choose $\alpha \in (0,1)$ as in Lemma 3.1, according to which there exists $c_{\alpha} > 0$ such that for every $c \in (0, c_{\alpha})$ and all $\delta > 0$, the function w_{δ} in (3.1) satisfies (3.2). Let $\delta \in (0, r_0)$ be arbitrary. Choose $0 < c < \min\{c_{\alpha}, \min_{x \in \partial B_{r_0}(0)}(u(x)/U_0(x))\}$. Clearly, $w_{\delta} = 0 < u$ on $\partial B_{\delta}(0)$. Our choice of c gives that $u \ge w_{\delta}$ on $\partial B_{r_0}(0)$. We now apply the comparison principle in Lemma 4.1 to obtain that

$$u(x) \ge w_{\delta}(x)$$
 for every $\delta \le |x| \le r_0$. (3.9)

For any $x \in B_{r_0}(0) \setminus \{0\}$, by letting $\delta \to 0$ in (3.9), we deduce that

$$u(x) \ge c U_0(x)$$
 for every $x \in B_{r_0}(0) \setminus \{0\}$,

which finishes the proof of (3.8).

Our next result is important in the proof of Theorem 1.3 to treat Case (\mathcal{U}) with $h \equiv 0$ in (1.14) (see Lemma 6.1) and to analyze Case (\mathcal{M}_2) in Lemma 6.3.

Lemma 3.3. In Case (\mathcal{U}) and Case (\mathcal{M}_2) for every $\alpha > 0$ small, depending on N, q, θ and λ , there exists $c_{\alpha} \in (0, 1)$ such that for any $c \in (0, c_{\alpha})$ and all $\delta > 0$, the function z_{δ} given by

$$z_{\delta}(x) := c U_0(x) \left[1 - \left(\frac{|x|}{\delta}\right)^{\alpha} \right]^{\frac{1}{\sqrt{\alpha}}} \quad for \ every \ 0 < |x| \le \delta$$
(3.10)

satisfies the following inequality

$$-\mathbb{L}_{\lambda}(z_{\delta}) + |x|^{\theta} (z_{\delta})^{q} \le 0 \quad \text{for every } 0 < |x| < \delta.$$

$$(3.11)$$

Proof. The claim follows from Lemma 3.1 by using the Kelvin transform.

4. Basic ingredients

We often use the following comparison principle, which is a consequence of Lemma 2.1 in [16].

Lemma 4.1 (Comparison Principle). Let $\lambda \in \mathbb{R}$, $N \geq 3$ and ω be a smooth bounded domain in \mathbb{R}^N with $\overline{\omega} \subseteq \mathbb{R}^N \setminus \{0\}$. Let $b \in C^{0,\tau}(\overline{\omega})$ satisfy b > 0 in ω , where $\tau \in (0,1)$. Assume that g is a real-valued continuous function on $(0,\infty)$ such that g(t)/t is increasing for t > 0.

If u and v are positive $C^1(\omega)$ -functions such that

$$\begin{cases} -\mathbb{L}_{\lambda}(u) + b(x) g(u) \leq 0 \leq -\mathbb{L}_{\lambda}(v) + b(x) g(v) \text{ in } \mathcal{D}'(\omega), \\ \limsup_{\text{dist}(x,\partial\omega) \to 0} [u(x) - v(x)] \leq 0, \end{cases}$$

then $u \leq v$ in ω .

Our next result is obtained in the same way as Lemma 4.1 in [13, Chapter 4], where we take $b(x) = |x|^{\theta}$ for $x \in \mathbb{R}^N \setminus \{0\}$ and $h(t) = t^q$ for every $t \in (0, \infty)$ with q > 1 and $\theta \in \mathbb{R}$.

Lemma 4.2 (A priori estimates). Let $r_0 > 0$ be such that $\overline{B_{2r_0}(0)} \subset \Omega_0$. For every q > 1and $\lambda, \theta \in \mathbb{R}$, there exists a constant $C_0 > 0$, depending only on N, q, λ and θ , such that any sub-solution u of (1.2) with $\Omega = \Omega_0$ satisfies

$$u(x) \le C_0 |x|^{-\Theta} \quad \text{for all } 0 < |x| \le r_0.$$
 (4.1)

Proof. Fix $x_0 \in \mathbb{R}^N$ with $0 < |x_0| \le r_0$. For every $x \in B_{|x_0|/2}(x_0)$, we define

$$\mathcal{P}(x) := C_0 |x_0|^{-\Theta} [\zeta(x)]^{-\frac{2}{q-1}}, \quad \text{where } \zeta(x) := 1 - \left(\frac{2|x-x_0|}{|x_0|}\right)^2.$$
(4.2)

We claim that in (4.2) we can take a constant $C_0 > 0$ that is independent of x_0 and r_0 such that

$$-\mathbb{L}_{\lambda}(\mathcal{P}(x)) + |x|^{\theta} \left(\mathcal{P}(x)\right)^{q} \ge 0 \quad \text{for every } x \in B_{|x_{0}|/2}(x_{0}).$$

$$(4.3)$$

Indeed, a simple calculation shows that the inequality in (4.3) is equivalent to

$$\frac{|x_0|^{\theta}}{|x|^{\theta}} \left\{ \frac{16}{q-1} \left[N\zeta(x) + \frac{8(q+1)}{q-1} \frac{|x-x_0|^2}{|x_0|^2} \right] + \lambda \frac{|x_0|^2}{|x|^2} \zeta^2(x) \right\} \le C_0^{q-1}$$
(4.4)

for every $x \in B_{|x_0|/2}(x_0)$. Since $1/2 \le |x|/|x_0| \le 3/2$ for each $x \in B_{|x_0|/2}(x_0)$, we see that the left-hand side of (4.4) is bounded above by a positive constant depending only on N, q, λ and θ .

Hence, we can find $C_0 > 0$ such that (4.3) holds. Let u be any sub-solution of (1.2) with $\Omega = \Omega_0$. From the definition of \mathcal{P} in (4.2), we have $\mathcal{P}(x) \to \infty$ as dist $(x, \partial B_{|x_0|/2}(x_0)) \to 0$. Then, by Lemma 4.1, we obtain that

$$u(x) \le \mathcal{P}(x)$$
 for every $x \in B_{|x_0|/2}(x_0)$. (4.5)

In particular, for $x = x_0$ we have $u(x_0) \leq \mathcal{P}(x_0) = C_0 |x_0|^{-\Theta}$. Since this inequality holds for every $0 < |x_0| \leq r_0$, we conclude the proof of (4.1).

Since the constant C_0 in Lemma 4.2 is independent of the domain, we obtain global a priori estimates for any positive solution of (1.2).

Corollary 4.3 (Global a priori estimates). Let $\Omega = \mathbb{R}^N$. For every q > 1 and $\lambda, \theta \in \mathbb{R}$, there exists a constant $C_0 > 0$, depending only on N, q, λ and θ , such that every positive sub-solution u of (1.2) satisfies

$$u(x) \le C_0 |x|^{-\Theta} \quad \text{for all } x \in \mathbb{R}^N \setminus \{0\}.$$

$$(4.6)$$

We next state a regularity result from [13, Lemma 4.9], proved there in a more general setting. We recall that a positive measurable function ϕ defined on some interval (0, A) with A > 0 is called regularly varying at zero with index $m \in \mathbb{R}$, or $\phi \in RV_m(0+)$ in short, provided that

$$\lim_{r \to 0^+} \frac{\phi(\xi r)}{\phi(r)} = \xi^m \quad \text{for every } \xi > 0.$$

When m = 0, we say that ϕ is slowly varying at zero. Any positive constant is a slowly varying function at zero. Non-trivial examples of slowly varying functions at zero (defined for r > 0small) include

- (a) the logarithm $\log(1/r)$, its iterates $\log_k(1/r)$ (defined as $\log(\log_{k-1}(1/r))$) and powers of $\begin{array}{l} \log_k(1/r) \text{ for every integer } k \ge 1; \\ \text{(b)} \ \exp\left(\frac{\log(1/r)}{\log\log(1/r)}\right); \\ \text{(c)} \ \exp[(-\log r)^{\nu}] \text{ for } \nu \in (0,1). \end{array}$

Lemma 4.4 (A regularity result). Let $r_0 > 0$ be such that $\overline{B_{4r_0}(0)} \subset \Omega_0$. Let $0 \leq \delta \leq \Theta$ and $g \in RV_{-\delta}(0+)$ be a positive continuous function on $(0, 4r_0)$ such that $\limsup_{|x|\to 0} |x|^{\Theta}g(r) < \infty$. If u is a solution of (1.2) with $\Omega = \Omega_0$ such that, for some constant $C_1 > 0$, we have

$$0 < u(x) \le C_1 g(|x|) \quad for \ every \ 0 < |x| < 2r_0, \tag{4.7}$$

then there exist constants C > 0 and $\alpha \in (0,1)$ such that

$$|\nabla u(x)| \le C \, \frac{g(|x|)}{|x|} \quad and \quad |\nabla u(x) - \nabla u(x')| \le C \, \frac{g(|x|)}{|x|^{1+\alpha}} \, |x - x'|^{\alpha} \tag{4.8}$$

for every x, x' in \mathbb{R}^N satisfying $0 < |x| \le |x'| < r_0$.

Remark 4.5. If in Lemma 4.4 we assume that (4.7) holds for $g \in RV_{-\delta}(0+)$ with $\delta \leq \Theta < 0$ or $\delta < 0 \leq \Theta$, then the assertion of (4.8) remains valid, subject to a slight change only in the second inequality, which should be replaced by

$$|\nabla u(x) - \nabla u(x')| \le C \frac{g(|x'|)}{|x|^{1+\alpha}} |x - x'|^{\alpha}$$

for every x, x' in \mathbb{R}^N satisfying $0 < |x| \le |x'| < r_0$. Here, and in the first inequality of (4.8), the constant C will depend on $|\delta|$ (only when $\delta < 0$). The explanation for these changes is provided in Remark 4.11 of [13, p. 34].

5. Proof of Theorem 1.1 and Theorem 1.2

The claim of Theorem 1.2 follows from Corollary 3.2 and Proposition 5.2. The ingredients necessary for proving the latter are given in Section 5.1. We conclude the assertion of Theorem 1.1 in Section 5.2 based on Theorem 1.2.

To simplify writing, by Case (\mathcal{M}) , we mean Case (\mathcal{M}_1) or Case (\mathcal{M}_2) . Here, we assume that either Case (\mathcal{M}) or Case (\mathcal{U}) holds, that is,

- $(\mathcal{M}) \ \lambda \leq \lambda_H \text{ and } \theta \in (-\infty, \theta_-) \cup (\theta_+, \infty);$
- $(\mathcal{U}) \ \lambda > \lambda_H$ and every $\theta \in \mathbb{R}$.

We construct refined local sub/super-solutions of (1.2) with $\Omega = B_1(0)$, which we use to fine-tune the behavior of the positive solutions of (1.2) near zero. We illustrate this point. In Case (\mathcal{M}) and Case (\mathcal{U}), we always have at our disposal the solution U_0 of (1.2). Using our super-solutions constructed in this section, jointly with the *a priori* estimates in Lemma 4.2, we obtain in Proposition 5.2 that every (sub-)solution of (1.2) with $\Omega = \Omega_0$ satisfies

$$\limsup_{|x| \to 0} \frac{u(x)}{U_0(x)} \le 1.$$
(5.1)

Moreover, using our refined local sub/super-solutions in Cases (\mathcal{U}) and (\mathcal{M}), we show that the proof of $\lim_{|x|\to 0} u(x)/U_0(x) = 1$ reduces to proving

$$\liminf_{|x| \to 0} \frac{u(x)}{U_0(x)} > 0.$$
(5.2)

5.1. Construction and motivation of our refined sub/super-solutions. The idea of constructing a suitable family of sub-solutions and super-solutions to obtain more precise upper and lower bound estimates near zero has been used successfully for various nonlinear elliptic equations without a Hardy potential, see for example [10, 12, 14, 15].

In our situation, the introduction of the Hardy potential in Case (\mathcal{U}) and Case (\mathcal{M}_1) poses an extra difficulty when comparing an arbitrary solution u of (1.2) with a super-solution (or subsolution). Such a comparison will take place on a punctured ball, $B_{r_0}(0) \setminus \{0\}$ with $r_0 \in (0, 1)$ small enough such that $\overline{B_{r_0}(0)} \subset \Omega$. To apply the comparison principle in Lemma 4.1, we need to ensure that the solution u is bounded above by the super-solution (and below by the sub-solution) on $\partial B_{r_0}(0)$ and also as $|x| \to 0$.

Let $\alpha > 0$ and $\nu > 0$ be fixed. For every $\varepsilon \in (0, 1)$ and $\eta > 0$, we define

$$w_{\varepsilon,\eta}^{+}(x) := (1+\varepsilon) U_{0}(x) |x|^{-\eta} \left(1 + \frac{|x|^{\alpha}}{\nu}\right)^{\frac{1}{\sqrt{\alpha}}},$$

$$w_{\varepsilon,\eta}^{-}(x) := (1-\varepsilon) U_{0}(x) |x|^{\eta} \left(1 + \frac{|x|^{\alpha}}{\nu}\right)^{-\frac{1}{\sqrt{\alpha}}},$$
(5.3)

for every $x \in \mathbb{R}^N \setminus \{0\}$, where U_0 is given by (1.5).

Assuming (5.2) and using the *a priori* estimates in Lemma 4.2, it is clear that we get the desired control *near zero* by introducing along $U_0(x)$ the factor $|x|^{\eta}$ in the sub-solution $w_{\varepsilon,\eta}^-$ and the factor $|x|^{-\eta}$ in the super-solution $w_{\varepsilon,\eta}^+$.

Even though for every $\varepsilon \in (0, 1)$ and $\eta > 0$, we find that $(1+\varepsilon) U_0(x)|x|^{-\eta}$ and $(1-\varepsilon) U_0(x)|x|^{\eta}$ is a super-solution and sub-solution of (1.2) in $B_1(0) \setminus \{0\}$, respectively, the shortcoming of these becomes apparent when comparing them with u on $\partial B_{r_0}(0)$. As we take $\eta \to 0$ and eventually $\varepsilon \to 0$, we need another degree of freedom to adjust the values of sub/super-solutions on $\partial B_{r_0}(0)$.

Previously, the above issue was resolved by adding to the super-solution a corrective term (itself a super-solution) such that its behavior near zero is dominated by U_0 . But only in Case (\mathcal{M}_2) this strategy can work as follows: we can add $C|x|^{-p_-}$ to the super-solution $(1+\varepsilon) U_0(x)|x|^{-\eta}$ (or to the solution u in order to control the sub-solution $(1-\varepsilon) U_0(x)|x|^{\eta}$), where C > 0 is a suitable constant depending on u and r_0 . This works well only in Case (\mathcal{M}_2) since then $|x|^{\Theta-p_-} \to 0$ as $|x| \to 0$ and $C|x|^{-p_-}$ is a super-solution of (1.2). But the above strategy does not work in Case (\mathcal{M}_1) or Case (\mathcal{U}) . Indeed, in Case (\mathcal{M}_1) we have $|x|^{\Theta-p_-} \to \infty$ as $|x| \to 0$, whereas p_- is not well-defined in Case (\mathcal{U}) when $\lambda > \lambda_H$. For this reason, we have to reshape our super-solutions and sub-solutions: we multiply $(1+\varepsilon) U_0(x)|x|^{-\eta}$ by an *extra* factor of the form $(1+|x|^{\alpha}/\nu)^{1/\sqrt{\alpha}}$ giving the super-solution $w_{\varepsilon,\eta}^+$ and correspondingly multiply $(1-\varepsilon) U_0(x)|x|^{\eta}$ by $(1 + |x|^{\alpha}/\nu)^{-1/\sqrt{\alpha}}$ to yield the sub-solution $w_{\varepsilon,\eta}^-$, where $\alpha > 0$ is fixed suitably small, depending only on N, q, θ and λ , while $\nu > 0$ is arbitrary. The verification that $w_{\varepsilon,\eta}^+$ and $w_{\varepsilon,\eta}^-$ is a super-solution and sub-solution of (1.2) in $B_1(0) \setminus \{0\}$, respectively, is done in Lemma 5.1. We can now choose $\nu > 0$ small, depending only on r_0, u, N, q, θ and λ , such that $w_{\varepsilon,\eta}^- \leq u \leq w_{\varepsilon,\eta}^+$ on $\partial B_{r_0}(0)$ for every $\varepsilon \in (0, 1)$ and $\eta > 0$ small. By the comparison principle in Lemma 4.1, we conclude (1.9).

We next proceed with the details.

Lemma 5.1. Assume Case (\mathcal{M}) or Case (\mathcal{U}) . Fix $\alpha > 0$ small, depending only on N, q, θ and λ . Let $\nu > 0$ be arbitrary. For every $\varepsilon \in (0, 1)$, there exists $\eta_0 = \eta_0(\varepsilon, N, q, \theta, \lambda) > 0$ such that

$$-\mathbb{L}_{\lambda}(w_{\varepsilon,\eta}^{+}) + |x|^{\theta}(w_{\varepsilon,\eta}^{+})^{q} \ge 0 \quad and \quad -\mathbb{L}_{\lambda}(w_{\varepsilon,\eta}^{-}) + |x|^{\theta}(w_{\varepsilon,\eta}^{-})^{q} \le 0$$
(5.4)

in $B_1(0) \setminus \{0\}$, for every $\eta \in (0, \eta_0)$.

Proof. Let $\alpha > 0$. For every $t \ge 0$ and $\eta > 0$, we define

$$G_{\eta}^{\pm}(t) := (1+t)^{-2\mp \frac{(q-1)}{\sqrt{\alpha}}} \left(A_{\eta}^{\pm} t^2 + B_{\eta}^{\pm} t + C_{\eta}^{\pm} \right),$$
(5.5)

where A_{η}^{\pm} , B_{η}^{\pm} and C_{η}^{\pm} are given by

$$\begin{cases} A_{\eta}^{\pm} := 1 \pm \frac{\sqrt{\alpha} \left(N - 2 - 2 \Theta \pm \sqrt{\alpha}\right)}{\ell} \mp \frac{\eta \left(N - 2 - 2 \Theta \mp \eta \pm 2\sqrt{\alpha}\right)}{\ell} \\ B_{\eta}^{\pm} := 2 \pm \frac{\sqrt{\alpha} \left(N - 2 - 2 \Theta + \alpha\right)}{\ell} \mp \frac{2 \eta \left(N - 2 - 2 \Theta \mp \eta \pm \sqrt{\alpha}\right)}{\ell}, \\ C_{\eta}^{\pm} := 1 \mp \frac{\eta \left(N - 2 - 2 \Theta \mp \eta\right)}{\ell}. \end{cases}$$

From the definition of G_{η}^{\pm} in (5.5), we find that

$$\frac{d}{dt}G_{\eta}^{\pm}(t) = \mp \frac{(q-1)}{\sqrt{\alpha}} (1+t)^{-3\mp \frac{(q-1)}{\sqrt{\alpha}}} \left(A_{\eta}^{\pm} t^2 + \widetilde{B}_{\eta}^{\pm} t + \widetilde{C}_{\eta}^{\pm}\right),$$

for every t>0, where $\widetilde{B}^{\pm}_{\eta}$ and $\widetilde{C}^{\pm}_{\eta}$ are defined by

$$\begin{cases} \widetilde{B}_{\eta}^{\pm} := \left(1 \pm \frac{\sqrt{\alpha}}{q-1}\right) B_{\eta}^{\pm} \mp \frac{2\sqrt{\alpha}}{q-1} A_{\eta}^{\pm} \\ \widetilde{C}_{\eta}^{\pm} := \left(1 \pm \frac{2\sqrt{\alpha}}{q-1}\right) C_{\eta}^{\pm} \mp \frac{\sqrt{\alpha}}{q-1} B_{\eta}^{\pm}. \end{cases}$$

We choose $\alpha > 0$ small enough, depending only on N, q, θ and λ , such that

$$\lim_{\eta \to 0} A_{\eta}^{\pm} > 0, \quad \lim_{\eta \to 0} \widetilde{B}_{\eta}^{\pm} > 0 \quad \text{and} \quad \lim_{\eta \to 0} \widetilde{C}_{\eta}^{\pm} > 0.$$

Hence, there exists $\eta_1 = \eta_1(N, q, \theta, \lambda) > 0$ such that A_{η}^{\pm} , \tilde{B}_{η}^{\pm} and \tilde{C}_{η}^{\pm} are all positive for every $\eta \in (0, \eta_1)$. Therefore, G_{η}^+ is decreasing on $(0, \infty)$, whereas G_{η}^- is increasing on $(0, \infty)$, leading to

$$\sup_{t \in (0,\infty)} G_{\eta}^{+}(t) = G_{\eta}^{+}(0) = C_{\eta}^{+} \text{ and } \inf_{t \in (0,\infty)} G_{\eta}^{-}(t) = G_{\eta}^{-}(0) = C_{\eta}^{-}.$$

By direct computations, we observe that (5.4) holds if and only if

$$|x|^{\eta(q-1)}G_{\eta}^{+}(|x|^{\alpha}/\nu) \le (1+\varepsilon)^{q-1} \text{ and } |x|^{-\eta(q-1)}G_{\eta}^{-}(|x|^{\alpha}/\nu) \ge (1-\varepsilon)^{q-1}$$
(5.6)

for every $|x| \in (0,1)$. Since $\lim_{\eta\to 0} C_{\eta}^{\pm} = 1$, we observe that there exists $\eta_0 \in (0,\eta_1)$ with η_0 depending on $\varepsilon, N, q, \theta$ and λ such that $C_{\eta}^+ \leq (1+\varepsilon)^{q-1}$ and $C_{\eta}^- \geq (1-\varepsilon)^{q-1}$ for every $\eta \in (0,\eta_0)$. Thus, (5.6) is satisfied for every 0 < |x| < 1 and all $\eta \in (0,\eta_0)$. This finishes the proof.

Proposition 5.2. In Case (\mathcal{M}) and Case (\mathcal{U}) , every positive solution of (1.2) with $\Omega = \Omega_0$ satisfies (5.1). In addition, we have

$$\liminf_{|x|\to 0} \frac{u(x)}{U_0(x)} > 0 \quad if and only if \quad \lim_{|x|\to 0} \frac{u(x)}{U_0(x)} = 1.$$
(5.7)

Proof. Let $r_0 \in (0,1)$ be such that $\overline{B_{r_0}(0)} \subset \Omega$. Fix $\alpha > 0$ as in Lemma 5.1. Let u be a positive solution of (1.2) in $\Omega \setminus \{0\}$. We choose $\nu = \nu(r_0, u, N, q, \theta, \lambda) > 0$ small such that the following two inequalities hold

$$\begin{cases} U_0(r_0) \left(1 + \frac{r_0^{\alpha}}{\nu}\right)^{-\frac{1}{\sqrt{\alpha}}} \leq \min_{x \in \partial B_{r_0}(0)} u(x) \\ U_0(r_0) \left(1 + \frac{r_0^{\alpha}}{\nu}\right)^{\frac{1}{\sqrt{\alpha}}} \geq \max_{x \in \partial B_{r_0}(0)} u(x). \end{cases}$$

Fix $\varepsilon \in (0,1)$ arbitrary. Let η_0 be given by Lemma 5.1. Our choice of $\nu > 0$ ensures that

$$w_{\varepsilon,\eta}^{-}(x) \le u(x) \le w_{\varepsilon,\eta}^{+}(x)$$
 for every $x \in \partial B_{r_0}(0)$ and every $\eta \in (0,\eta_0)$, (5.8)

where $w_{\varepsilon,\eta}^+$ and $w_{\varepsilon,\eta}^-$ are defined in (5.3). Using Lemma 4.2, we find that

$$\lim_{|x|\to 0} \frac{u(x)}{w_{\varepsilon,\eta}^+(x)} = 0.$$
(5.9)

Moreover, if $\liminf_{|x|\to 0} u(x)/U_0(x) > 0$, then we find in addition that

$$\lim_{|x| \to 0} \frac{w_{\varepsilon,\eta}^{-}(x)}{u(x)} = 0.$$
(5.10)

In view of (5.4) and (5.8)–(5.10), by the comparison principle in Lemma 4.1, we infer that

$$w_{\varepsilon,\eta}^{-}(x) \le u(x) \le w_{\eta,\varepsilon}^{+}(x) \quad \text{for every } 0 < |x| \le r_0 \text{ and all } \eta \in (0,\eta_0).$$
(5.11)

For every $x \in B_{r_0}(0) \setminus \{0\}$ fixed, by letting $\eta \to 0$ in (5.11), we arrive at

$$(1-\varepsilon)\left(1+\frac{|x|^{\alpha}}{\nu}\right)^{-\frac{1}{\sqrt{\alpha}}} \le \frac{u(x)}{U_0(x)} \le (1+\varepsilon)\left(1+\frac{|x|^{\alpha}}{\nu}\right)^{\frac{1}{\sqrt{\alpha}}}.$$

Thus, for every $\varepsilon \in (0, 1)$, it follows that

$$1 - \varepsilon \le \liminf_{|x| \to 0} \frac{u(x)}{U_0(x)} \le \limsup_{|x| \to 0} \frac{u(x)}{U_0(x)} \le 1 + \varepsilon.$$

Hence, by passing to the limit $\varepsilon \to 0$, we conclude that $\lim_{|x|\to 0} u(x)/U_0(x) = 1$ as desired. This completes the proof.

Remark 5.3. In the framework of Proposition 5.2, every solution u of (1.2) satisfies (5.1). On the other hand, to prove that $\lim_{|x|\to 0} u(x)/U_0(x) = 1$, the hypothesis $\liminf_{|x|\to 0} u(x)/U_0(x) > 0$ is necessary and we cannot dispense with in Case (\mathcal{M}_2) . To see this, we draw attention to Case (\mathcal{M}_2) in Theorem 2.1 when a solution u of (1.2) may satisfy **(A)** $\lim_{|x|\to 0} |x|^{p-}u(x) \in (0,\infty)$ or **(B)** $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma \in (0,\infty)$ (and then $\lim_{|x|\to 0} u(x)/U_0(x) = 0$). Theorem 1.3 shows that there exist solutions for (1.2) in each of the situations outlined in Theorem 2.1. 5.2. **Proof of Theorem 1.1.** Let $\Omega = \mathbb{R}^N$. We show that U_0 in (1.5) is the only solution of (1.2) in Case (\mathcal{U}). Let u be a solution of (1.2). Let $\varepsilon \in (0, 1)$ be arbitrary. By Theorem 1.2, u satisfies (1.9). Then, using the Kelvin transform (see Section 2), we obtain (1.13). Hence, there exist $R_{\varepsilon} > r_{\varepsilon} > 0$ such that

$$(1-\varepsilon)U_0(x) \le u(x) \le (1+\varepsilon)U_0(x) \quad \text{for every } |x| \in (0, r_\varepsilon] \cup [R_\varepsilon, \infty). \tag{5.12}$$

Since U_0 is a positive solution of (1.2), we find that

$$-\mathbb{L}_{\lambda}((1+\varepsilon)U_0) + |x|^{\theta}(1+\varepsilon)^{q}U_0^{q} \ge 0 \quad \text{in } \mathbb{R}^N \setminus \{0\}$$

and, similarly,

$$-\mathbb{L}_{\lambda}((1-\varepsilon)U_0) + |x|^{\theta}(1-\varepsilon)^{q}U_0^{q} \le 0 \quad \text{in } \mathbb{R}^N \setminus \{0\}.$$

Hence, the comparison principle in Lemma 4.1 gives that the inequalities in (5.12) hold for every $x \in \mathbb{R}^N \setminus \{0\}$. By letting $\varepsilon \to 0$, we arrive at $u \equiv U_0$ in $\mathbb{R}^N \setminus \{0\}$. This ends the proof of Theorem 1.1.

6. Proof of Theorem 1.3

Our aim is to prove the assertions of Theorem 1.3 on problem (1.14), namely,

$$\begin{cases} -\Delta u - \frac{\lambda}{|x|^2} u + |x|^{\theta} u^q = 0 & \text{in } \Omega \setminus \{0\}, \\ u = h \ge 0 & \text{on } \partial\Omega, \quad u > 0 & \text{in } \Omega \setminus \{0\}, \end{cases}$$
(6.1)

where throughout this section, $\Omega \subseteq \mathbb{R}^N$ is a smooth bounded domain containing zero. In Lemma 6.1 we establish the first three statements in Theorem 1.3, whereas the last one regarding Case (\mathcal{M}_2) is proved separately in Lemma 6.3.

Lemma 6.1. Suppose that $h \in C(\partial \Omega)$ is a non-negative function.

(1) Let Case (U) hold. Then, there exists a unique solution u_h of problem (6.1). Moreover, if $\Theta < (N-2)/2$ and $h \equiv 0$, then $u_h(x)/|x|$ and $|x|^{\theta+1}u_h^q$ belong to $L^2(\Omega)$, $u_h \in H_0^1(\Omega)$ and, for every $\varphi \in H_0^1(\Omega)$,

$$\int_{\Omega} \nabla u_h \cdot \nabla \varphi \, dx - \int_{\Omega} \frac{\lambda}{|x|^2} u_h \, \varphi \, dx + \int_{\Omega} |x|^{\theta} u_h^q \, \varphi \, dx = 0.$$
(6.2)

- (2) Assume Case (\mathcal{M}_1) or Case (\mathcal{N}) . If $h \neq 0$ on $\partial\Omega$, then problem (6.1) has a unique solution u_h .
- (3) If $h \equiv 0$ on $\partial\Omega$, then (6.1) has no solutions in Case (\mathcal{M}_1) and Case (\mathcal{N}) .

Proof. We divide the proof into four steps.

Step 1. In Cases $(\mathcal{U}), (\mathcal{M}_1)$ and (\mathcal{N}) , there is at most one solution of (6.1).

Proof of Step 1. We show that any two solutions u_h and U_h of (6.1) coincide.

In Cases (\mathcal{U}) and (\mathcal{M}_1), we derive from Theorem 1.2, that $u_h(x)/U_h(x) \to 1$ as $|x| \to 0$. Since $u_h = U_h = h$ on $\partial\Omega$, the comparison principle in Lemma 4.1 yields that, for every $\varepsilon \in (0, 1)$,

$$(1-\varepsilon) U_h \le u_h \le (1+\varepsilon) U_h$$
 in $\Omega \setminus \{0\}$.

Thus, by passing to the limit with $\varepsilon \to 0$, we arrive at $u_h = U_h$ in $\Omega \setminus \{0\}$.

In Case (\mathcal{N}) by Theorem 2.1 we have $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = 0$ with $u = u_h$ and $u = U_h$. This means that for every $\varepsilon > 0$, there exists $r_{\varepsilon} > 0$ small such that $u_h(x) \le \varepsilon \Phi_{\lambda}^+(x)$ for every $0 < |x| \le r_{\varepsilon}$. By Lemma 4.1, it follows that $u_h \le \varepsilon \Phi_{\lambda}^+ + U_h$ in $\Omega \setminus \{0\}$. By letting $\varepsilon \to 0$ and then interchanging u_h and U_h , we arrive at $u_h = U_h$ in $\Omega \setminus \{0\}$ as desired. **Step 2.** Problem (6.1) has a solution u_h in Case (\mathcal{U}) and, moreover, if $h \neq 0$ also in Cases (\mathcal{M}_1) and (\mathcal{N}).

Proof of Step 2. We will obtain a solution u_h of (6.1) as the limit $k \to \infty$ of a non-increasing sequence $\{u_{h,k}\}_{k\geq k_0}$ of solutions to boundary value problems (see (6.3)) on approximate domains $\Omega_k := \Omega \setminus \overline{B_{1/k}(0)}$ for $k \geq k_0$ large.

In Cases (\mathcal{U}) and (\mathcal{M}_1) , we know from Theorem 1.2 that, whenever it exists, a solution of (6.1) satisfies $\lim_{|x|\to 0} |x|^{\Theta} u(x) = \ell^{1/(q-1)}$. This provides the inspiration for taking the boundary value problems in (6.3). It is useful to remark that if C > 0 is large enough, then $C|x|^{-\Theta}$ is always a super-solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$. In Cases $(\mathcal{U}), (\mathcal{M}_1)$ and (\mathcal{M}_2) , we need only choose $C \geq \ell^{1/(q-1)}$. In Case (\mathcal{N}) , we can take any C > 0 since $\ell \leq 0$.

If necessary, we increase C > 0 to ensure that $C \ge \max_{x \in \partial \Omega} |x|^{\Theta} h(x)$. Fix $\delta > 0$ small such that $\overline{B_{\delta}(0)} \subset \Omega$. Let k_0 be a positive integer such that $1/k_0 < \delta$. Then, for every integer $k \ge k_0$, the following boundary value problem

$$\begin{cases} -\Delta u - \frac{\lambda}{|x|^2} u + |x|^{\theta} u^q = 0 & \text{in } \Omega_k := \Omega \setminus \overline{B_{1/k}(0)}, \\ u = h & \text{on } \partial\Omega, \\ u(x) = C |x|^{-\Theta} & \text{for every } |x| = 1/k, \\ u > 0 & \text{in } \Omega_k \end{cases}$$
(6.3)

has a unique solution $u_{h,k} \in C^2(\Omega_k) \cap C(\overline{\Omega_k})$. This assertion is true for all $\lambda, \theta \in \mathbb{R}$ and q > 1. The existence of a non-negative solution $u_{h,k}$ follows from Theorem 15.18 in Gilbarg and Trudinger [27], whereas the strong maximum principle (see, for example, Theorem 2.5.1 in [32]) yields the positivity of $u_{h,k}$ in Ω_k . The uniqueness of $u_{h,k}$ is a consequence of Lemma 4.1. Moreover, with our choice of C, we obtain that

$$u_{h,k+1} \le u_{h,k} \le C |x|^{-\Theta}$$
 in Ω_k for every $k \ge k_0$.

Using Lemma 4.4 (see also Remark 4.5) and a standard argument, we get that, up to a subsequence, $u_{h,k} \to u_h$ in $C^1_{\text{loc}}(\Omega \setminus \{0\})$ as $k \to \infty$, where u_h is a non-negative solution of (6.1).

It remains to prove that $u_h > 0$ in $\Omega \setminus \{0\}$. We treat Case (\mathcal{U}) separately from Case (\mathcal{M}_1) and Case (\mathcal{N}).

• In Cases (\mathcal{M}_1) and (\mathcal{N}) we assume that $h \neq 0$ on $\partial\Omega$. Then, by the strong maximum principle, we conclude that u_h is positive in $\Omega \setminus \{0\}$.

• In Case (\mathcal{U}) our argument works for any non-negative function $h \in C(\partial\Omega)$ since we have Lemma 3.3 at our disposal. More precisely, for fixed $c \in (0, c_{\alpha})$ as in Lemma 3.3 and $\delta > 0$ chosen above, we define z_{δ} as in (3.10). Since (3.11) holds, by Lemma 4.1, we derive that

$$u_{h,k}(x) \ge z_{\delta}(x)$$
 for every $1/k \le |x| \le \delta$ and all $k \ge k_0$. (6.4)

Thus, by letting $k \to \infty$ in (6.4), we find that $u_h(x) \ge z_{\delta}(x) > 0$ for every $0 < |x| < \delta$. This gives that $\liminf_{|x|\to 0} u_h(x)/U_0(x) > 0$. By the strong maximum principle, we have $u_h > 0$ in $\Omega \setminus \{0\}$. This concludes Step 2.

Step 3. If $\Theta < (N-2)/2$ in Case (\mathcal{U}) and h = 0, then $u_h(x)/|x|$ and $|x|^{\theta+1}u_h^q$ belong to $L^2(\Omega)$, $u_h \in H_0^1(\Omega)$ and (6.2) holds.

Proof of Step 3. Let $\Theta < (N-2)/2$ in Case (\mathcal{U}) . By Theorem 1.2, u_h satisfies (1.9) and thus $u_h(x)/|x|$ and $|x|^{\theta+1}(u_h(x))^q$ belong to $L^2(\Omega)$. Hence, using that $\varphi(x)/|x| \in L^2(\Omega)$ for every $\varphi \in H_0^1(\Omega)$, we see that $u_h(x) \varphi(x)/|x|^2$ and $|x|^{\theta} (u_h(x))^q \varphi(x)$ belong to $L^1(\Omega)$. Using Lemma 4.4 when $0 \leq \Theta < (N-2)/2$ and Remark 4.5 when $\Theta < 0$ (where $g(r) = r^{\Theta}$ for r > 0),

we obtain

$$|\nabla u_h(x)| \le C|x|^{-\Theta - 1}$$
 for every $0 < |x| < r_0$, (6.5)

where $r_0 > 0$ is small. This implies that $u_h \in H^1_{loc}(\Omega)$. For every $\varepsilon \in (0, 1)$ small, let w_{ε} be a non-decreasing and smooth function on $(0, \infty)$ such that

$$\begin{cases} w_{\varepsilon} = 0 & \text{on } (0, \varepsilon], \\ 0 < w_{\varepsilon}(r) < 1 & \text{for every } r \in (\varepsilon, 2\varepsilon) \\ w_{\varepsilon} = 1 & \text{on } [2\varepsilon, \infty). \end{cases}$$

Let $\varphi \in C_c^1(\Omega)$ be arbitrary. Using $\varphi w_{\varepsilon} \in C_c^1(\Omega \setminus \{0\})$ as a test function in the equation (1.2) satisfied by u_h , we deduce that

$$\int_{\Omega} w_{\varepsilon} \nabla u_h \cdot \nabla \varphi \, dx - \int_{\Omega} \frac{\lambda}{|x|^2} u_h \, \varphi \, w_{\varepsilon} \, dx + \int_{\Omega} |x|^{\theta} u_h^q \, \varphi \, w_{\varepsilon} \, dx = -J_{\varepsilon}, \tag{6.6}$$

where for every $\varepsilon > 0$, we define J_{ε} as follows

$$J_{\varepsilon} := \int_{\Omega} \varphi \, \nabla u_h \cdot \nabla w_{\varepsilon} \, dx = \int_{\{\varepsilon < |x| < 2\varepsilon\}} \varphi(x) \, \frac{w'_{\varepsilon}(|x|)}{|x|} \, \nabla u_h(x) \cdot x \, dx.$$

With the estimate in (6.5) and relying on the assumption $\Theta < (N-2)/2$, it is easy to see that $J_{\varepsilon} \to 0$ as $\varepsilon \to 0$. Hence, by letting $\varepsilon \to 0$ in (6.6), we infer that (6.2) holds for every $\varphi \in C_c^1(\Omega)$.

We now assume that h = 0 in (6.1). Instead of u_h , we use the notation u_0 . We claim that $u_0 \in H_0^1(\Omega)$ and (6.2) holds for each $\varphi \in H_0^1(\Omega)$.

Let $\delta > 0$ be small such that $\overline{B_{\delta}(0)} \subset \Omega$. We define $\omega = \Omega \setminus \overline{B_{\delta}(0)}$. By the classical trace theory, there exists a function $f \in H^1(\omega) \cap C(\overline{\omega})$ such that $f = u_0$ on $\partial \omega$. By the classical regularity theory, we infer that $u_0 \in H^1(\omega)$. This proves that $u_0 \in H^1(\Omega)$. Since $u_0 = 0$ on $\partial \Omega$, we conclude that $u_0 \in H_0^1(\Omega)$.

Now, for each $\varphi \in H_0^1(\Omega)$, there exists a sequence $\{\varphi_n\}_{n\geq 1}$ in $C_c^1(\Omega)$ such that $\varphi_n \to \varphi$ in $H^1(\Omega)$ as $n \to \infty$. Then, by the Hardy inequality in (1.1),

$$\int_{\Omega} \frac{(\varphi_n - \varphi)^2}{|x|^2} \, dx \to 0 \quad \text{as } n \to \infty.$$

Hence, by Hölder's inequality, as $n \to \infty$, we find that

$$\int_{\Omega} \frac{u_0}{|x|^2} \varphi_n \, dx \to \int_{\Omega} \frac{u_0}{|x|^2} \varphi \, dx \text{ and } \int_{\Omega} |x|^{\theta} u_0^q \varphi_n \, dx \to \int_{\Omega} |x|^{\theta} u_0^q \varphi \, dx. \tag{6.7}$$

For the second limit in (6.7) we also use that $\sup_{x\in\Omega} |x|^{\theta+2}(u_0(x))^{q-1} < \infty$ in view of (1.9) and $u_0 = 0$ on $\partial\Omega$. Since (6.2) holds with φ_n instead of φ , by letting $n \to \infty$, we extend (6.2) to every $\varphi \in H_0^1(\Omega)$. This finishes Step 3.

Step 4. If $h \equiv 0$, then (6.1) has no solution in Case (\mathcal{M}_1) and Case (\mathcal{N}).

Proof of Step 4. Suppose that u is a solution of (6.1) with h = 0 in Case (\mathcal{M}_1) or Case (\mathcal{N}) . Then, in Case (\mathcal{M}_1) we have $\Theta < p_-$ so that Theorem 1.2 implies that $\lim_{|x|\to 0} |x|^{p_-} u(x) = 0$. Hence, for every $\varepsilon > 0$, we obtain that $u(x) \le \varepsilon |x|^{-p_-}$ for |x| > 0 close to zero and for every $x \in \partial \Omega$. The comparison principle (in Lemma 4.1) gives that $0 < u(x) \le \varepsilon |x|^{-p_-}$ for every $x \in \Omega \setminus \{0\}$. By letting $\varepsilon \to 0$, we arrive at $u \equiv 0$ in $\Omega \setminus \{0\}$, which is a contradiction.

The same argument applies in Case (\mathcal{N}) whenever $\theta = \theta_{-} \leq \theta_{+}$ since from Theorem 2.1, we have $\lim_{|x|\to 0} |x|^{p_{-}} u(x) = 0$. In the remaining situation of Case (\mathcal{N}) , namely, when $\theta_{-} < \theta \leq \theta_{+}$ (relevant for $\lambda < \lambda_{H}$), we use that $\lim_{|x|\to 0} |x|^{p_{+}} u(x) = 0$. The above ideas work with p_{+} instead of p_{-} so that $0 < u(x) \leq \varepsilon |x|^{-p_{+}}$ for every $x \in \Omega \setminus \{0\}$ and every $\varepsilon > 0$. Hence, we again obtain a contradiction by letting $\varepsilon \to 0$. This completes the proof of Step 4 and, hence, of Lemma 6.1. \Box

Remark 6.2. Despite the similarity revealed in Theorem 1.2 between Case (\mathcal{U}) and Case (\mathcal{M}_1) , the difference between these comes to the fore when considering the problem (6.1) with h = 0, which has no solutions in Case (\mathcal{M}_1) . We give an alternative proof using the Hardy inequality. Assume by contradiction that problem (6.1) with h = 0 on $\partial\Omega$ has a solution u_0 in Case (\mathcal{M}_1) . Observe that $\Theta < (N-2)/2$ holds in Case (\mathcal{M}_1) . In view of Theorem 1.2, the argument used in Step 3 for Case (\mathcal{U}) applies to Case (\mathcal{M}_1) . Hence, $u_0 \in H_0^1(\Omega)$ and by taking $\varphi = u_0$ in (6.2), we get

$$\int_{\Omega} |\nabla u_0|^2 \, dx - \int_{\Omega} \frac{\lambda}{|x|^2} u_0^2 \, dx + \int_{\Omega} |x|^{\theta} u_0^{q+1} \, dx = 0.$$
(6.8)

Since $u_0 > 0$ in $\Omega \setminus \{0\}$ and $\lambda \leq \lambda_H$ in Case (\mathcal{M}_1) , the Hardy inequality in (1.1) yields a contradiction. This proof breaks down in Case (\mathcal{U}) when $\lambda > \lambda_H$.

Lemma 6.3. Let $h \in C(\partial\Omega)$ be a non-negative function. Assume Case (\mathcal{M}_2) . Then, for each $\gamma \in (0, \infty]$ (also for $\gamma = 0$ if $h \neq 0$), problem (6.1), subject to

$$\lim_{|x|\to 0} \frac{u(x)}{\Phi_{\lambda}^+(x)} = \gamma \tag{6.9}$$

has a unique solution $u_h^{(\gamma)}$. For $\gamma = \infty$, we have $\lim_{|x|\to 0} u_h^{(\gamma)}(x)/U_0(x) = 1$.

- (1) If $h \neq 0$ on $\partial\Omega$, then the set of all solutions of (6.1) is $\{u_h^{(\gamma)}: 0 \leq \gamma \leq \infty\}$, where for $\gamma = 0$ we have $\lim_{|x|\to 0} |x|^{p_-} u_h^{(\gamma)}(x) \in (0,\infty)$.
- (2) If $h \equiv 0$ on $\partial\Omega$, then the set of all solutions of (6.1) is $\{u_h^{(\gamma)}: 0 < \gamma \leq \infty\}$.

Proof. We first show that for $\gamma = \infty$, problem (6.1), subject to (6.9), has a unique solution $u_h^{(\gamma)}$. By Theorem 2.1, any such solution $u_h^{(\gamma)}$ must satisfy $\lim_{|x|\to 0} u_h^{(\gamma)}(x)/U_0(x) = 1$. To construct $u_h^{(\gamma)}$, we proceed exactly like in Step 2 in the proof of Lemma 6.1 in Case (\mathcal{U}) replacing u_h by $u_h^{(\gamma)}$. Thus, we obtain a solution $u_h^{(\gamma)}$ of (6.1) satisfying $u_h^{(\gamma)}(x) \ge z_{\delta}(x)$ for every $0 < |x| < \delta$. Recall that z_{δ} is given by Lemma 3.3. It follows that $\liminf_{|x|\to 0} u_h^{(\gamma)}(x)/U_0(x) > 0$. Then, by Proposition 5.2, we conclude that $\lim_{|x|\to 0} u_h^{(\gamma)}(x)/U_0(x) = 1$ as desired. The uniqueness of such a solution is a simple consequence of Lemma 4.1 (see Step 1 in the proof of Lemma 6.1).

Let $\gamma \in (0, \infty)$ be arbitrary. We prove that (6.1), subject to (6.9) has a solution $u_h^{(\gamma)}$, which is unique by Lemma 4.1. To construct $u_h^{(\gamma)}$, we follow the argument in the proof of [13, Lemma 5.6]. For the reader's convenience, we give the details. From Lemma 4.1 and [13, Propositions 3.1(c) and 3.4(c)], there exists a unique positive (radial) solution \underline{u}_{γ} for the problem

$$\begin{cases} -\Delta u - \frac{\lambda}{|x|^2} u + |x|^{\theta} u^q = 0 & \text{in } B_1(0) \setminus \{0\}, \\ u = 1 & \text{on } \partial B_1(0), \\ \lim_{|x| \to 0} \frac{u(x)}{\Phi_{\lambda}^+(x)} = \gamma. \end{cases}$$
(6.10)

Fix $\delta \in (0,1)$ such that $\overline{B_{\delta}(0)} \subset \Omega$. Choose a constant C > 0 large such that

 $C\Phi_{\lambda}^{-} \ge h \text{ on } \partial\Omega \quad \text{and} \quad C\Phi_{\lambda}^{-} \ge \underline{u}_{\gamma} \text{ on } \partial B_{\delta}(0).$ (6.11)

Based on the second inequality in (6.11), we derive from Lemma 4.1 that

$$\underline{u}_{\gamma} \le \gamma \Phi_{\lambda}^{+} + C \Phi_{\lambda}^{-} \quad \text{in } B_{\delta}(0). \tag{6.12}$$

Let $k_0 > 1/\delta$. For each integer $k \ge k_0$, the boundary value problem

$$\begin{cases}
-\Delta u - \frac{\lambda}{|x|^2} u + |x|^{\theta} u^q = 0 & \text{in } \Omega_k := \Omega \setminus \overline{B_{1/k}(0)}, \\
u = h & \partial\Omega, \\
u = \gamma \Phi_{\lambda}^+ + C \Phi_{\lambda}^- & \text{on } \partial B_{1/k}(0), \\
u > 0 & \text{in } \Omega_k
\end{cases}$$
(6.13)

has a unique solution $u_{h,k}^{(\gamma)} \in C^2(\Omega_k) \cap C(\overline{\Omega_k})$. By Lemma 4.1, we see that

$$u_{h,k+1}^{(\gamma)} \le u_{h,k}^{(\gamma)} \le \gamma \Phi_{\lambda}^{+} + C \Phi_{\lambda}^{-} \quad \text{in } \Omega_{k} \text{ for every } k \ge k_{0}.$$
(6.14)

As before, we obtain that, up to a subsequence, $u_{h,k}^{(\gamma)}$ converges to $u_h^{(\gamma)}$ in $C^1_{\text{loc}}(\Omega \setminus \{0\})$ as $k \to \infty$, where $u_h^{(\gamma)}$ is a non-negative solution of (6.1).

From our choice of C, (6.12) and Lemma 4.1, we infer that

$$\underline{u}_{\gamma}(x) \leq C \Phi_{\lambda}^{-}(x) + u_{h,k}^{(\gamma)}(x) \quad \text{for every} \ \ 1/k \leq |x| \leq \delta.$$

By letting $k \to \infty$ and using that $\lim_{|x|\to 0} \underline{u}_{\gamma}(x)/\Phi_{\lambda}^+(x) = \gamma$, we arrive at

$$\liminf_{|x|\to 0} \frac{u_h^{(\gamma)}(x)}{\Phi_\lambda^+(x)} \ge \gamma$$

Moreover, from (6.14), we find that $\limsup_{|x|\to 0} u_h^{(\gamma)}(x)/\Phi_{\lambda}^+(x) \leq \gamma$. Hence, $u_h^{(\gamma)}$ is a solution of (6.1), subject to (6.9).

We next take $\gamma = 0$ and assume that $h \not\equiv 0$ on $\partial\Omega$. Let C > 0 be large so that the first inequality in (6.11) holds. As before, we consider (6.13) (with $\gamma = 0$) and obtain a non-negative solution $u_h^{(\gamma)}$ of (6.1) satisfying (6.14). It follows that $\lim_{|x|\to 0} u_h^{(\gamma)}(x)/\Phi_{\lambda}^+(x) = 0$ and since $h \not\equiv 0$ on $\partial\Omega$, by the strong maximum principle, we infer that $u_h^{(\gamma)} > 0$ in Ω . By Theorem 2.1, we have $\lim_{|x|\to 0} |x|^{p-} u_h^{(\gamma)}(x) \in (0,\infty)$. Moreover, there exists a unique solution for (6.1), subject to (6.9) with $\gamma = 0$. Indeed, if u_0 and U_0 are two such solutions, then by Lemma 4.1, we have $u_0 \leq \varepsilon \Phi_{\lambda}^+ + U_0$ in $\Omega \setminus \{0\}$ for arbitrary $\varepsilon > 0$. It follows that $u_0 \leq U_0$ in $\Omega \setminus \{0\}$. By interchanging u_0 and U_0 , we conclude that $u_0 \equiv U_0$ in $\Omega \setminus \{0\}$.

To finish the proof of Lemma 6.3, it remains to show that if $h \equiv 0$ on $\partial\Omega$ and $\gamma = 0$, then (6.1), subject to (6.9), has no solutions. Indeed, if such a solution u were to exist, then for every $\varepsilon > 0$, we would have $u(x) \leq \varepsilon \Phi_{\lambda}^+(x)$ for every $x \in \Omega \setminus \{0\}$, which would lead to $u \equiv 0$ in Ω by letting $\varepsilon \to 0$. This is a contradiction. The proof of Lemma 6.3 is now complete.

7. Proof of Theorem 1.4

As explained in Section 2, by using the Kelvin transform, it suffices to establish the assertions of Theorem 1.4 in Case (\mathcal{M}_2) , which we state below.

Proposition 7.1 (Multiplicity, Case (\mathcal{M}_2)). Let $\Omega = \mathbb{R}^N$ and Case (\mathcal{M}_2) hold, that is, $\lambda \leq \lambda_H$ and $\theta > \theta_+$. Then, for every $\gamma \in (0, \infty)$, problem (1.2), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$, has a unique solution u_{γ} , which is radially symmetric and satisfies (1.13), that is, $\lim_{|x|\to\infty} u_{\gamma}(x)/U_0(x) =$ 1. In addition, we have

$$\begin{cases} u_{\gamma} \leq u_{\gamma'} \leq U_0 & \text{in } \mathbb{R}^N \setminus \{0\} \quad \text{for every } 0 < \gamma < \gamma' < \infty, \\ U_0(x) = \lim_{\gamma \to \infty} u_{\gamma}(x) \quad \text{for each } x \in \mathbb{R}^N \setminus \{0\}. \end{cases}$$
(7.1)

The set S of all positive solutions of (1.2) is $S = \{U_0\} \cup \{u_\gamma : \gamma \in (0, \infty)\}.$

Proof. We split the proof into three steps. The first one deals with the existence and uniqueness of the solution u_{γ} of (1.2), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$. The claim of (7.1) is proved in Step 2. The asymptotic behavior of u_{γ} in (1.13) follows from Theorem 2.2, while the radial symmetry of u_{γ} follows from uniqueness and radial symmetry of the problem (1.2). In Step 3 we show that U_0 and $\{u_{\gamma}: \gamma \in (0, \infty)\}$ make up all the positive solutions of (1.2).

Step 1. For every $\gamma \in (0, \infty)$, there exists a unique solution u_{γ} for problem (1.2), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$.

Proof of Step 1. We fix $\gamma \in (0, \infty)$ and show that any solutions u and \tilde{u} of (1.2), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$, must coincide. Let $\varepsilon > 0$ be arbitrary.

We define $v_{\varepsilon}(x) := (1 + \varepsilon) \widetilde{u}(x) + \varepsilon \Phi_{\lambda}^{-}(x)$ for every $x \in \mathbb{R}^{N} \setminus \{0\}$. It is easy to check that v_{ε} satisfies

$$\mathbb{L}_{\lambda}(v_{\varepsilon}) + |x|^{\theta} (v_{\varepsilon}(x))^{q} \ge 0 \quad \text{for every } x \in \mathbb{R}^{N} \setminus \{0\}.$$

From $\lim_{|x|\to 0} u(x)/\tilde{u}(x) = 1$, there exists $r_{\varepsilon} > 0$ small such that

$$u(x) \le (1+\varepsilon) \widetilde{u}(x) \le v_{\varepsilon}(x)$$
 for every $0 < |x| \le r_{\varepsilon}$.

The assumption $\theta > \theta_+$ yields that $\Theta > p_+ \ge p_-$. Hence, by Corollary 4.3, there exists $R_{\varepsilon} > 0$ large such that $u(x) \le \varepsilon |x|^{-p_-} \le v_{\varepsilon}(x)$ for every $|x| \ge R_{\varepsilon}$. Then, by Lemma 4.1 with $\omega := \{x \in \mathbb{R}^N : r_{\varepsilon} < |x| < R_{\varepsilon}\}$, we find that

$$u(x) \le v_{\varepsilon}(x) \quad \text{for every } x \in \mathbb{R}^N \setminus \{0\}.$$
 (7.2)

For $x \in \mathbb{R}^N \setminus \{0\}$ fixed, letting $\varepsilon \to 0$ in (7.2), we obtain that $u \leq \tilde{u}$ in $\mathbb{R}^N \setminus \{0\}$. By interchanging u and \tilde{u} , we conclude that $u \equiv \tilde{u}$ in $\mathbb{R}^N \setminus \{0\}$.

We next prove that for arbitrary $\gamma \in (0, \infty)$, there exists a solution u_{γ} of problem (1.2), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$. By Theorem 1.3, for every $\gamma \in (0, \infty)$ and $k \ge 1$, there exists a unique solution $u_{k,\gamma}$ for the problem

$$\begin{cases}
-\mathbb{L}_{\lambda}(u) + |x|^{\theta}u^{q} = 0 \quad \text{in } B_{k}(0) \setminus \{0\}, \\
\lim_{|x| \to 0} \frac{u(x)}{\Phi_{\lambda}^{+}(x)} = \gamma, \\
u = 0 \quad \text{on } \partial B_{k}(0), \\
u > 0 \quad \text{in } B_{k}(0) \setminus \{0\}.
\end{cases}$$
(7.3)

Moreover, $u_{k,\gamma}$ is radially symmetric in $B_k(0) \setminus \{0\}$. Recall that U_0 in (1.5) is a solution of (1.2) and $\lim_{|x|\to 0} U_0(x)/\Phi_{\lambda}^+(x) = \infty$ since we are in Case (\mathcal{M}_2). By the comparison principle in Lemma 4.1, we have

$$0 < u_{k,\gamma} \le u_{k+1,\gamma} \le U_0 \quad \text{in } B_k(0) \setminus \{0\}.$$
(7.4)

By a standard argument, we deduce that, up to a subsequence, $u_{k,\gamma} \to u_{\gamma}$ in $C^{1}_{\text{loc}}(\mathbb{R}^{N} \setminus \{0\})$ as $k \to \infty$. Moreover, u_{γ} is a radial solution of (1.2). From (7.4) and $\lim_{|x|\to 0} u_{k,\gamma}(x)/\Phi^{+}_{\lambda}(x) = \gamma$ for each $k \geq 1$, we find that

$$\liminf_{|x|\to 0} \frac{u_{\gamma}(x)}{\Phi_{\lambda}^+(x)} \ge \gamma.$$
(7.5)

For every $\varepsilon > 0$, we define $w_{\varepsilon}(x) := (\gamma + \varepsilon) \Phi_{\lambda}^+(x) + U_0(1) \Phi_{\lambda}^-(x)$ for every $0 < |x| \le 1$. Since w_{ε} is a super-solution of (1.2) in $B_1(0) \setminus \{0\}$ such that $u_{k,\gamma}(x) \le w_{\varepsilon}(x)$ whenever |x| = 1, by Lemma 4.1, we deduce that

$$u_{k,\gamma}(x) \le w_{\varepsilon}(x) \quad \text{for every } 0 < |x| < 1 \text{ and all } k \ge 1.$$
 (7.6)

For $x \in B_1(0) \setminus \{0\}$ fixed, we have $u_{\gamma}(x) \leq w_{\varepsilon}(x)$ by letting $k \to \infty$ in (7.6). This proves that $\limsup_{|x|\to 0} u_{\gamma}(x)/\Phi_{\lambda}^+(x) \leq \gamma + \varepsilon$. Letting $\varepsilon \to 0$, jointly with (7.5), we find that $\lim_{|x|\to 0} u_{\gamma}(x)/\Phi_{\lambda}^+(x) = \gamma$. This ends the proof of Step 1.

Step 2. Proof of (7.1).

Proof of Step 2. Since $\lim_{|x|\to 0} U_0(x)/\Phi_{\lambda}^+(x) = \infty$ and u_{γ} satisfies (1.13), from Lemma 4.1 we deduce that

$$u_{\gamma} \le u_{\gamma'} \le U_0 \quad \text{in } \mathbb{R}^N \setminus \{0\} \quad \text{for every } 0 < \gamma < \gamma' < \infty.$$
 (7.7)

To show that $u_{\gamma} \to U_0$ pointwise in $\mathbb{R}^N \setminus \{0\}$ as $\gamma \to \infty$, it suffices to show that for every sequence $\{\gamma_j\}_{j\geq 1}$ with $\lim_{j\to\infty} \gamma_j = \infty$, there exists a subsequence of $\{u_{\gamma_j}\}$ (relabeled $\{u_{\gamma_j}\}$) that converges pointwise to U_0 in $\mathbb{R}^N \setminus \{0\}$. Without loss of generality, we can assume that $\{\gamma_j\}_{j\geq 1}$ is increasing to ∞ . Then, using (7.7) as before, we find that, up to a subsequence, $\{u_{\gamma_j}\}_{j\geq 1}$ converges in $C^1_{\text{loc}}(\mathbb{R}^N \setminus \{0\})$ to a positive solution u_{∞} of (1.2), which satisfies $\lim_{|x|\to 0} u_{\infty}(x)/\Phi^+_{\lambda}(x) = \infty$. Then, Theorem 2.1 gives that $\lim_{|x|\to 0} u_{\infty}(x)/U_0(x) = 1$. With the same argument as in Step 1, we infer that $u_{\infty} \equiv U_0$ in $\mathbb{R}^N \setminus \{0\}$. This finishes Step 2.

Step 3. The set S of all solutions of (1.2) is $S = \{U_0\} \cup \{u_\gamma : \gamma \in (0, \infty)\}.$

Proof of Step 3. In Case (\mathcal{M}_2) , given any solution u of (1.2), exactly one of the alternatives **(A)**, **(B)** and **(C)** in Theorem 2.1 holds. The alternative **(C)** arises from the case $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \infty$. The fact that U_0 is the only positive solution of (1.2) in the situation **(C)** proceeds exactly as in Step 1 for the uniqueness of u_{γ} . Option **(B)** corresponds to u_{γ} with $\gamma \in (0, \infty)$.

We show that option (\mathbf{A}) is not viable, that is, problem (1.2) has no solutions satisfying

$$\lim_{|x| \to 0} \frac{u(x)}{\Phi_{\lambda}^{+}(x)} = 0.$$
(7.8)

From the assumption $\theta > \theta_+$, we have $\Theta > p_+$. Hence, Theorem 2.2 gives that

$$\lim_{|x| \to \infty} |x|^{p_+} u(x) = 0.$$
(7.9)

We reach a contradiction by showing that u = 0 in $\mathbb{R}^N \setminus \{0\}$. Let $\varepsilon > 0$ be arbitrary. Given the definition of Φ_{λ}^+ in (1.7), we distinguish two cases:

(i) Let $\lambda < \lambda_H$. If $V_{\varepsilon}(x) := \varepsilon \Phi_{\lambda}^+(x) = \varepsilon |x|^{-p_+}$ for each $x \in \mathbb{R}^N \setminus \{0\}$, then $\lim_{|x|\to 0} u(x)/V_{\varepsilon}(x) = 0$ in view of (7.8). For every $x \in \mathbb{R}^N \setminus \{0\}$, we have

$$-\mathbb{L}_{\lambda}(V_{\varepsilon}) + |x|^{\theta} (V_{\varepsilon})^{q} = |x|^{\theta} (V_{\varepsilon})^{q} \ge 0.$$
(7.10)

Since $\lim_{|x|\to\infty} u(x)/V_{\varepsilon}(x) = 0$, by Lemma 4.1, we have

$$u(x) \leq V_{\varepsilon}(x) = \varepsilon |x|^{-p_+}$$
 for all $x \in \mathbb{R}^N \setminus \{0\}$.

By letting $\varepsilon \to 0$ we arrive at $u \equiv 0$ in $\mathbb{R}^N \setminus \{0\}$, which is a contradiction.

(ii) Let $\lambda = \lambda_H$, that is, $p_- = p_+ = (N-2)/2$. Then, from (7.9), for every $\varepsilon > 0$ fixed, there exists $R_{\varepsilon} > 0$ large such that $u(x) \leq \varepsilon |x|^{-p_-}$ for every $|x| \geq R_{\varepsilon}$. For every $0 < |x| \leq R_{\varepsilon}$, we define

$$V_{\varepsilon}(x) := \frac{\varepsilon}{R_{\varepsilon}} |x|^{-p_{-}} \log\left(\frac{R_{\varepsilon}}{|x|}\right) + \varepsilon |x|^{-p_{-}}.$$

Using the definition of Φ_{λ}^+ in (1.7), we remark that V_{ε} satisfies (7.10) for every $0 < |x| < R_{\varepsilon}$. From (7.8), we observe that $\lim_{|x|\to 0} u(x)/V_{\varepsilon}(x) = 0$ and also $u(x) \leq \varepsilon |x|^{-p_-} = V_{\varepsilon}(x)$ for every $|x| = R_{\varepsilon}$. Thus, Lemma 4.1 gives that

$$u(x) \le V_{\varepsilon}(x)$$
 for every $0 < |x| \le R_{\varepsilon}$. (7.11)

Now, $R_{\varepsilon} \to \infty$ as $\varepsilon \searrow 0$ so that for every fixed $x \in \mathbb{R}^N \setminus \{0\}$, we have $0 < |x| < R_{\varepsilon}$ for every $\varepsilon > 0$ small enough. Hence, by letting $\varepsilon \to 0$ in (7.11), we arrive at $u \equiv 0$ in $\mathbb{R}^N \setminus \{0\}$.

Since in both cases we find a contradiction, we conclude that in Case (\mathcal{M}_2) , equation (1.2) has no positive solutions with $\lim_{|x|\to 0} |x|^{p-} u(x) \in (0,\infty)$. This finishes the proof of Step 3.

From Step 1–Step 3, we conclude the proof of Proposition 7.1.

8. Proof of Theorem 1.5

Let $\Omega = \mathbb{R}^N$. We show that (1.2) has no solutions in Case (\mathcal{N}), that is, if $\lambda \leq \lambda_H$ and $\theta_- \leq \theta \leq \theta_+$. Suppose by contradiction that u is a solution of (1.2). By Theorem 2.2, we have

$$\lim_{|x| \to \infty} |x|^{p_{-}} u(x) = 0, \tag{8.1}$$

whereas at zero, we derive from Theorem 2.1 that

$$\lim_{|x|\to 0} |x|^{p_-} u(x) = 0 \quad \text{if } \theta = \theta_-,$$

$$\lim_{|x|\to 0} |x|^{\Theta} u(x) = 0 \quad \text{if } \theta_- < \theta \le \theta_+.$$
(8.2)

Let $\varepsilon > 0$ be arbitrary. For all $x \in \mathbb{R}^N \setminus \{0\}$, we define

$$V_{\varepsilon}(x) := \begin{cases} \varepsilon |x|^{-p_{-}} & \text{if } \theta = \theta_{-}, \\ \varepsilon |x|^{-\Theta} + \varepsilon |x|^{-p_{-}} & \text{if } \theta_{-} < \theta \le \theta_{+}. \end{cases}$$

Recall that $\Phi_{\lambda}^{-}(x) = |x|^{-p_{-}}$ satisfies $\mathbb{L}_{\lambda}(\Phi_{\lambda}^{-}) = 0$ in $\mathbb{R}^{N} \setminus \{0\}$. On the other hand, the assumption $\theta_{-} \leq \theta \leq \theta_{+}$ implies that $\ell \leq 0$, where ℓ is given by (1.4), which means that $\varepsilon |x|^{-\Theta}$ is a supersolution of (1.2) since

$$-\mathbb{L}_{\lambda}(|x|^{-\Theta}) = -\ell |x|^{-\Theta-2} \ge 0 \quad \text{in } \mathbb{R}^{N} \setminus \{0\}.$$

Consequently, for every $\theta_{-} \leq \theta \leq \theta_{+}$, we have

$$-\mathbb{L}_{\lambda}(V_{\varepsilon}) + |x|^{\theta} (V_{\varepsilon})^{q} \ge 0 \quad \text{for every } x \in \mathbb{R}^{N} \setminus \{0\}.$$

From (8.1) and (8.2), we find that

$$\lim_{|x|\to 0} u(x)/V_{\varepsilon}(x) = 0 \quad \text{and} \quad \lim_{|x|\to\infty} u(x)/V_{\varepsilon}(x) = 0.$$

Hence, by the comparison principle in Lemma 4.1, we have

$$u(x) \le V_{\varepsilon}(x) \quad \text{for every } x \in \mathbb{R}^N \setminus \{0\}.$$
 (8.3)

Fixing $x \in \mathbb{R}^N \setminus \{0\}$ and letting $\varepsilon \to 0$ in the above inequality, we see that $u \equiv 0$ in $\mathbb{R}^N \setminus \{0\}$, which is a contradiction with the positivity of u. This completes the proof of Theorem 1.5.

9. Comments and remarks

In the study of equation (1.2), it is customary to assume $\theta > -2$. Singular solutions arise precisely in this range, see Remark 9.3, and thus the methods available in the literature for analyzing problem (1.2) are often adapted to $\theta > -2$. In this paper, we treat (1.2) for every $\lambda, \theta \in \mathbb{R}$, by distinguishing four cases: (\mathcal{U}), (\mathcal{M}_1), (\mathcal{M}_2) and (\mathcal{N}). For the latter three cases, we compare θ with the critical exponents θ_{\pm} defined in (1.3). Hence, we need to carefully design our techniques based on sub/super-solutions so that they work in a unified manner, without depending on any behavior of the solutions near zero.

To facilitate a comparison of our results with previous ones in the literature and to highlight the influence of the Hardy potential $\lambda |\cdot|^{-2}$ in (1.2), we express the findings of this paper by treating $\theta \in \mathbb{R}$ and q > 1 as fixed parameters and letting λ vary in \mathbb{R} . From this perspective, when $\Omega = \mathbb{R}^N$ in (1.2) we gain a threshold for λ , denoted by $\lambda^* = \lambda^*(N, \theta, q)$ defined as follows

$$\lambda^* := \lambda_H - \left(\frac{N-2}{2} - \frac{\theta+2}{q-1}\right)^2 = \Theta\left(N - 2 - \Theta\right).$$
(9.1)

For problem (1.2) with $\Omega = \mathbb{R}^N$ (or for (1.14)), a real number will be called a *threshold* for λ if the existence of solutions happens if and only if λ is (strictly) greater than that number.

Note that $\lambda^* \leq \lambda_H$ with equality if and only if $q = q_{N,\theta}$, where we define

$$q_{N,\theta} := \frac{N+2\theta+2}{N-2}.$$
(9.2)

Clearly, $q_{N,\theta} > 1$ if and only if $\theta > -2$, which means that for $\theta \leq -2$, the structure of the solutions of (1.2) is less varied. Theorems 1.1, 1.4 and 1.5 show that (1.2) with $\Omega = \mathbb{R}^N$ admits solutions if and only if $\lambda > \lambda^*$. If, moreover, $\lambda > \lambda_H$, then U_0 is the unique solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$. On the other hand, when $\lambda^* < \lambda \leq \lambda_H$ (for $q \neq q_{N,\theta}$), then (1.2) with $\Omega = \mathbb{R}^N$ has infinitely many solutions and all its solutions are radially symmetric. Their asymptotic behavior near zero and at infinity is specified in Corollary 9.1.

Corollary 9.1. Fix $\theta \in \mathbb{R}$ and q > 1. Let $\lambda \in \mathbb{R}$ be arbitrary. Problem (1.2) with $\Omega = \mathbb{R}^N$ has solutions if and only if $\lambda > \lambda^*$ and, in this case, the structure of all solutions is as follows:

- 1. If $\lambda > \lambda_H$, then U_0 in (1.5) is the only solution of problem (1.2).
- 2. If $\lambda^* < \lambda \leq \lambda_H$ (whenever $q \neq q_{N,\theta}$), then all the solutions are radially symmetric and the set of all solutions of problem (1.2) is given by

$$U_0 \cup \{U_{\gamma,q,\lambda} : \gamma \in (0,\infty)\},\$$

where we have

(a) If $q < q_{N,\theta}$ only for $\theta > -2$, then $U_{\gamma,q,\lambda}$ is the unique solution of problem (1.2) that satisfies

$$\lim_{|x|\to 0} \frac{U_{\gamma,q,\lambda}(x)}{\Phi_{\lambda}^+(x)} = \gamma \in (0,\infty) \quad and \quad \lim_{|x|\to\infty} \frac{U_{\gamma,q,\lambda}(x)}{U_0(x)} = 1.$$
(9.3)

(b) If $q > \max\{q_{N,\theta}, 1\}$, then $U_{\gamma,q,\lambda}$ is the unique solution of problem (1.2) that satisfies

$$\lim_{|x|\to 0} \frac{U_{\gamma,q,\lambda}(x)}{U_0(x)} = 1 \quad and \quad \lim_{|x|\to\infty} \frac{|x|^{N-2} U_{\gamma,q,\lambda}(x)}{\Phi_{\lambda}^+(1/|x|)} = \gamma \in (0,\infty).$$
(9.4)

Remark 9.2. For $\lambda = 0$, q > 1 and $\theta > -2$, Corollary 9.1 shows the following:

(I) Problem (1.2) with $\Omega = \mathbb{R}^N$ has no solutions if $q \ge (N+\theta)/(N-2)$; this fact follows from [15, Theorem 1.3] (with p = 2 there) or from the celebrated paper of Brezis and Véron [6] when $\theta = 0$, using also that every solution tends to zero at infinity by Corollary 4.3.

(II) Problem (1.2) with $\Omega = \mathbb{R}^N$ has infinitely many solutions, all radially symmetric, if $1 < q < (N+\theta)/(N-2)$; moreover, in this case, the set of all solutions is $U_0 \cup \{U_{\gamma,q} : \gamma \in (0,\infty)\}$, where for each $\gamma \in (0,\infty)$, the (radially symmetric) solution $U_{\gamma,q}$ of (1.2) satisfies

$$\lim_{|x|\to 0} |x|^{N-2} U_{\gamma,q}(x) = \gamma \quad and \quad \lim_{|x|\to \infty} \frac{U_{\gamma,q}(x)}{U_0(x)} = 1.$$

Hence, for $\lambda = \theta = 0$ in Case (II) above, we regain Theorem 3.2 of Friedman and Véron [23] (with p = 2 there) and also reveal the precise rate at which $U_{\gamma,q}$ vanishes at infinity, namely

$$\lim_{|x| \to \infty} |x|^{2/(q-1)} U_{\gamma,q} = \frac{2}{q-1} \left(\frac{2}{q-1} - N + 2 \right).$$

Remark 9.3. (i) For $\theta = -2$ in Corollary 9.1, we have $\lambda^* = 0$ and $U_0 \equiv \lambda^{1/(q-1)}$. If $\theta = -2$ (respectively, $\theta < -2$), then whenever it exists, every solution of problem (1.2) with $\Omega = \mathbb{R}^N$ is radially symmetric and converges to $\lambda^{1/(q-1)}$ as $|x| \to 0$ (respectively, vanishes at zero precisely like U_0).

(ii) On the other hand, for $\theta > -2$ every solution of problem (1.2) in $\mathbb{R}^N \setminus \{0\}$, whenever it exists (see Corollary 9.1), is radially symmetric, blows-up at zero and vanishes at infinity.

We now review Theorem 1.3 on the structure of all solutions for the problem

$$\begin{cases} -\Delta u - \frac{\lambda}{|x|^2} u + |x|^{\theta} u^q = 0 \text{ in } \Omega \setminus \{0\},\\ u = h \text{ on } \partial\Omega, \quad u > 0 \text{ in } \Omega \setminus \{0\}, \end{cases}$$
(9.5)

where $\Omega \subset \mathbb{R}^N$ is a smooth bounded domain containing the origin and h is a non-negative and continuous function on $\partial\Omega$. We separate $\theta > -2$ from $\theta \leq -2$ to underscore the changes that occur when going from one case to the other. In Corollaries 9.4 and 9.5 we assume h = 0 in (9.5). When $h \neq 0$ in (9.5), the structure of all solutions is discussed in Corollaries 9.7 and 9.8.

Corollary 9.4. Let $\theta > -2$, q > 1 and $\lambda \in \mathbb{R}$. Define $q_{N,\theta}$ as in (9.2). Suppose that h = 0 in problem (9.5).

- 1. If $\lambda > \lambda_H$, then problem (9.5) has a unique solution u_0 and, moreover, we have $\lim_{|x|\to 0} u_0(x)/U_0(x) = 1$.
- 2. If $q \ge q_{N,\theta}$, then for every $\lambda \le \lambda_H$, problem (9.5) has no solutions.
- 3. Let $1 < q < q_{N,\theta}$.
 - (a) If $\lambda^* < \lambda \leq \lambda_H$, then all the solutions of problem (9.5) are given by $\{u^{(\gamma)}: 0 < \gamma \leq \infty\}$, where $u^{(\gamma)}$ is the unique solution of (9.5), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$. When $\gamma = \infty$, we have

$$\lim_{|x| \to 0} \frac{u^{(\gamma)}(x)}{U_0(x)} = 1.$$

(b) If $\lambda \leq \lambda^*$, then problem (9.5) has no solutions.

Corollary 9.5. Fix $\theta \leq -2$ and q > 1. Let $\lambda \in \mathbb{R}$ be arbitrary. Assume that h = 0 in problem (9.5).

- 1. If $\lambda > \lambda_H$, then problem (9.5) has a unique solution u_0 and, moreover, we have $\lim_{|x|\to 0} u_0(x)/U_0(x) = 1$.
- 2. If $\lambda \leq \lambda_H$, then problem (9.5) has no solutions.

Remark 9.6. For problem (1.2) with $\Omega = \mathbb{R}^N$, we observe from Corollary 9.1 that $\lambda^* = \lambda^*(N, q, \theta)$ in (9.1) is the threshold for λ no matter how we fix $\theta \in \mathbb{R}$ and q > 1. In addition, unless $q = q_{N,\theta}$ (relevant for $\theta > -2$), we see that the threshold λ^* is less than λ_H .

On the other hand, when considering problem (9.5) with h = 0, the threshold for λ becomes λ_H for every $\theta \in \mathbb{R}$ and $q > \max\{q_{N,\theta}, 1\}$.

To complete our comparison, we next consider $h \neq 0$ in (9.5).

Corollary 9.7. Fix $\theta > -2$ and q > 1. Assume $h \neq 0$ in (9.5). Then, for every $\lambda \in \mathbb{R}$, problem (9.5) has at least a solution u_h .

(I) There is only one solution u_h exactly in the following cases:

(a)
$$\lambda > \lambda_H$$
; (b) $\lambda^* < \lambda \le \lambda_H$ and $q > q_{N,\theta}$; (c) $\lambda \le \lambda^*$. (9.6)

In cases (a) and (b), the solution u_h satisfies $\lim_{|x|\to 0} u_h(x)/U_0(x) = 1$. Furthermore, in case (c), we distinguish three situations:

- (c₁) If $\lambda = \lambda^*$ and $q > q_{N,\theta}$, then u_h satisfies (2.2).
- (c₂) If $\lambda = \lambda^*$ and $q = q_{N,\theta}$, then u_h satisfies (2.3).
- (c₃) If $(\lambda = \lambda^* \text{ and } q < q_{N,\theta})$ or $\lambda < \lambda^*$, then $\lim_{|x| \to 0} |x|^{p_-} u_h(x) \in (0,\infty)$.
- (II) For $\lambda^* < \lambda \leq \lambda_H$ and $q < q_{N,\theta}$, the set of all solutions of (9.5) is $\{u_h^{(\gamma)}: 0 \leq \gamma \leq \infty\}$, where $u_h^{(\gamma)}$ is the unique solution of (9.5), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$. We have $\lim_{|x|\to 0} u_h^{(\gamma)}(x)/U_0(x) = 1$ if $\gamma = \infty$ and $\lim_{|x|\to 0} |x|^{p_-} u_h^{(\gamma)}(x) \in (0,\infty)$ if $\gamma = 0$.

Corollary 9.8. Fix $\theta \leq -2$ and q > 1. Assume $h \neq 0$ in (9.5). Then, for every $\lambda \in \mathbb{R}$, there exists a unique solution u_h for (9.5). Moreover, we have:

- (i) If $\lambda > \lambda^*$, then $u_h(x)/U_0(x) \to 1$ as $|x| \to 0$.
- (ii) If $\lambda = \lambda^*$, then u_h satisfies (2.2);
- (iii) If $\lambda < \lambda^*$, then $\lim_{|x|\to 0} |x|^{p-} u_h(x) \in (0,\infty)$.

Remark 9.9. Let $\theta, \lambda \in \mathbb{R}$ and q > 1. No solution of (9.5) with $h \neq 0$ can be extended as a solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$ in the situations below:

- (1) $\lambda \leq \lambda^*$;
- (2) $\lambda > \lambda_H$ and $h \not\equiv U_0|_{\partial\Omega}$.

On the other hand, if $\lambda^* < \lambda \leq \lambda_H$ (for $q \neq q_{N,\theta}$), then we see that

- (1) for $q > \max\{q_{N,\theta}, 1\}$, the unique solution u_h of (9.5) can be extended to a solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$ provided that either $h = U_0|_{\partial\Omega}$ or $h = U_{\gamma,q,\lambda}|_{\partial\Omega}$ for some $\gamma \in (0,\infty)$, where $U_{\gamma,q,\lambda}$ is the unique solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$ that satisfies (9.4).
- (2) for $q < q_{N,\theta}$ (only when $\theta > -2$) and every $\gamma \in (0,\infty]$ (but not for $\gamma = 0$), the unique solution $u_h^{(\gamma)}$ of (9.5), subject to $\lim_{|x|\to 0} u(x)/\Phi_{\lambda}^+(x) = \gamma$ can be extended to a solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$ provided that $h = U_0|_{\partial\Omega}$ for $\gamma = \infty$ and $h = U_{\gamma,q,\lambda}|_{\partial\Omega}$ for $\gamma \in (0,\infty)$, where $U_{\gamma,q,\lambda}$ is here the unique solution of (1.2) in $\mathbb{R}^N \setminus \{0\}$ that satisfies (9.3).

These facts follow by comparing Corollaries 9.7 and 9.8 with Corollary 9.1.

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